## From Technologies to Markets

TA Sensor fusion for autonomous autonomous behicles ACTIVE

December 15<sup>th</sup>, 2020



## AGENDA

- I. Introduction
- 2. Radar
- 3. The proliferation of camera modules
- 4. The emergence of LiDAR
- 5. The transformation of E/E architecture
- 6. Market forecasts for ADAS vehicles sensors
- 7. LiDAR for robotic and industrial applications
- 8. Sensor fusion

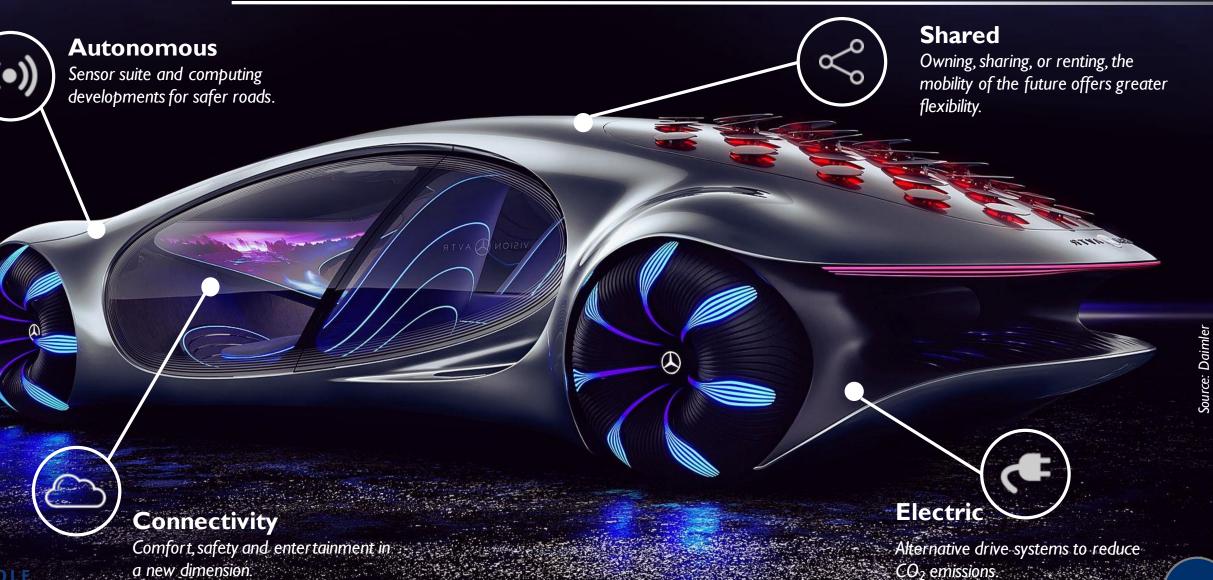


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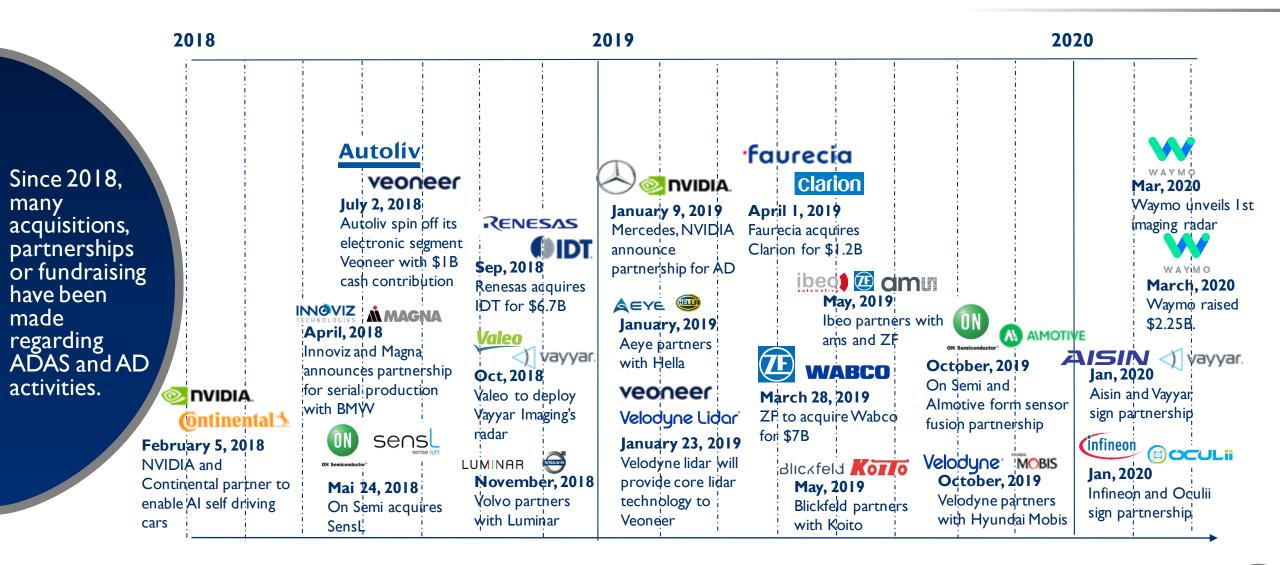
## CONTEXT

## C.A.S.E., the acronym taking over the auto industry



## SENSORS IN ADAS VEHICLES

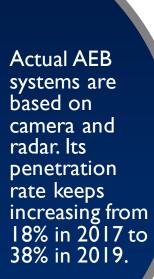
## Noteworthy news

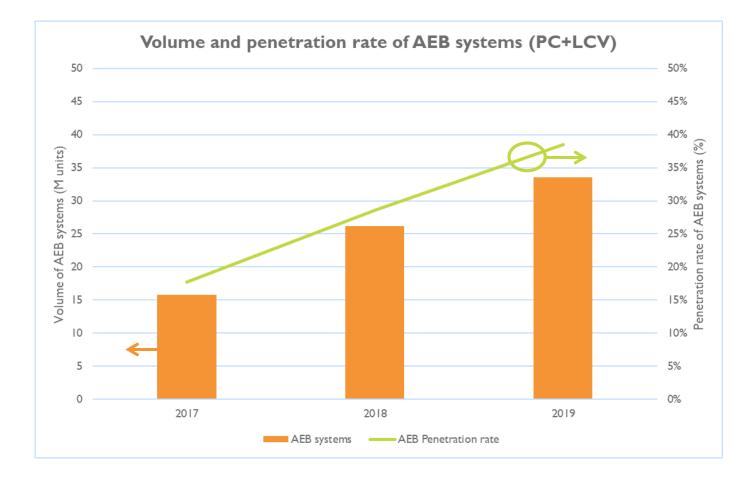




## SENSORS IN ADAS VEHICLES

## Volume and penetration rate of AEB systems





AEB systems based on:





Long Range Radar



## SENSORS IN ADAS VEHICLES

## AEB is still perfectible

- In October 2019, the American Automobile Association (AAA) conducted a series of tests using vehicles with AEB and pedestrian detection alerts on a closed course with dummy pedestrians.
- Several tests have been made at different speeds, mixing adult and children 'pedestrians' during daylight and night conditions.
- Tests were performed on: Chevy Malibu, Honda Accord, Tesla Model 3 and Toyota Camry.

Cars with high-tech safety systems are still really bad at not running people over.



A dummy pedestrian struck by a vehicle during the test. Source: AAA

New sensors like LiDAR or thermal cameras will need to be implemented

**60%** of the time, the vehicle struck the **adult** crossing the road during daylight at 20 mph.

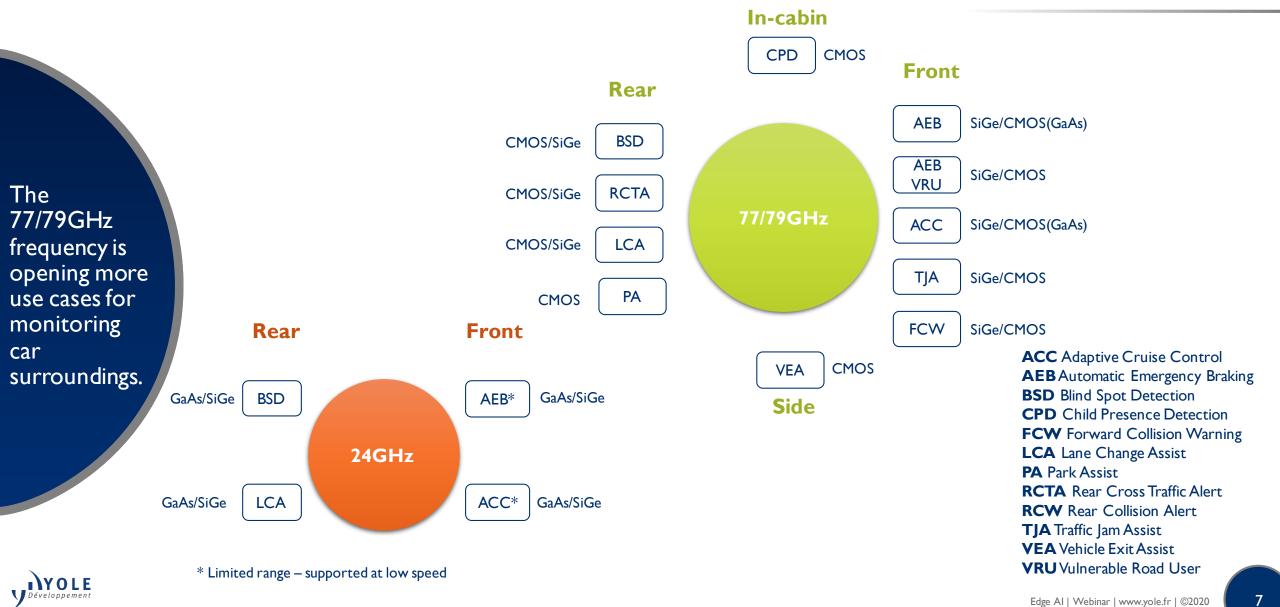
**89%** of the time, the vehicle struck the **child** crossing the road during daylight at 20 mph.

100% of the time, the vehicle struck the **adult** after a right turn at 15 mph.

When encountering an adult pedestrian **at night**, these systems were **ineffective**.

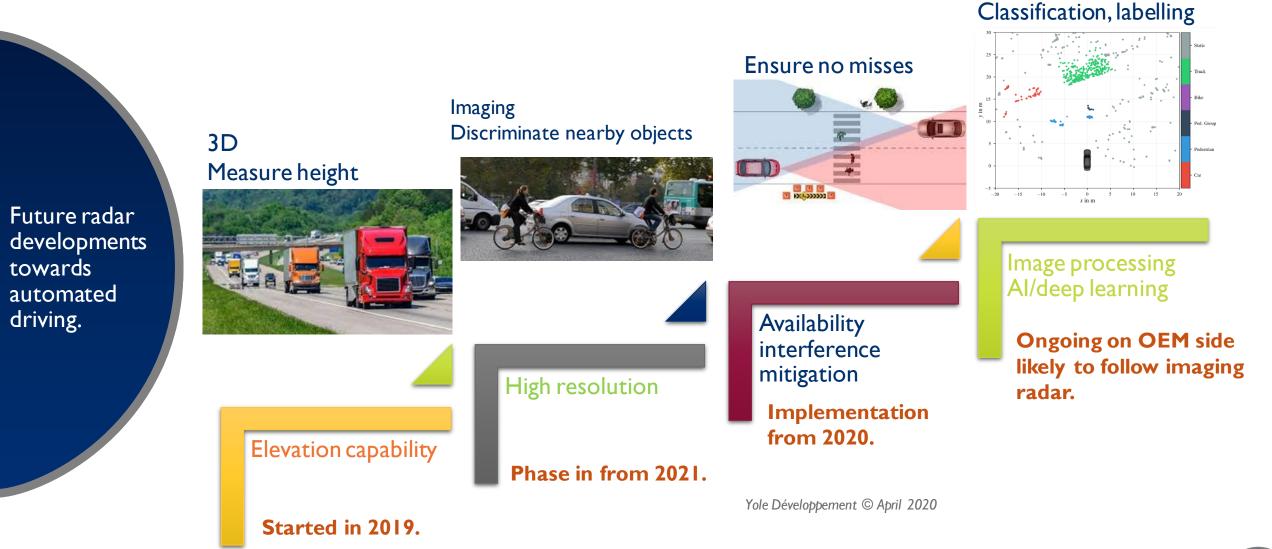
## CURRENT RADAR TECHNOLOGIES AND USE CASES

Which technology for which application?



## FUTURE RADAR TRENDS

Four steps towards super sensors

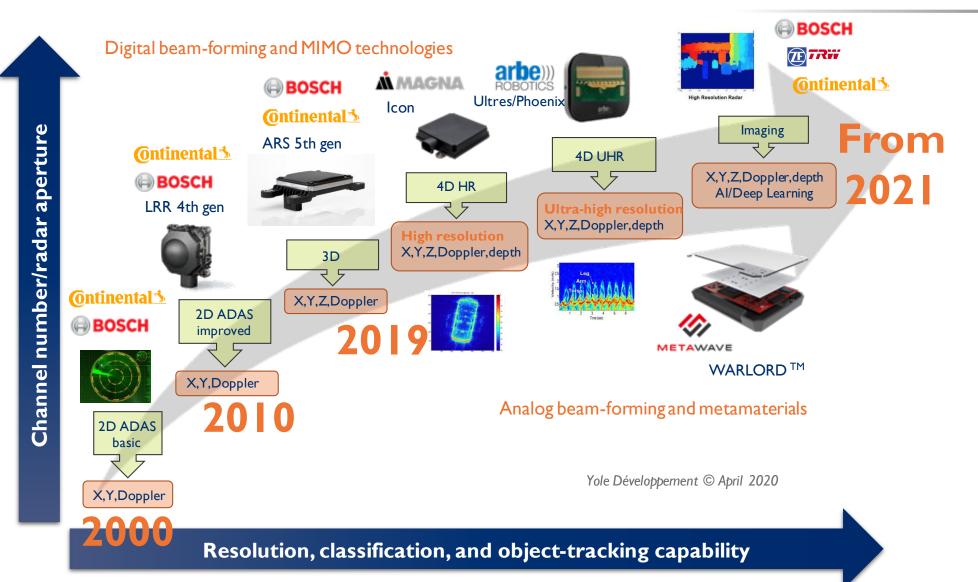




## FUTURE RADAR TRENDS

## The road to high resolution

Leveraging military and telecom technologies, advanced radar technology fully supports up to level-4 autonomy, with high resolution and radar imaging reaching the market with low C-SWAP.



## **RADAR MARKET SHARES**

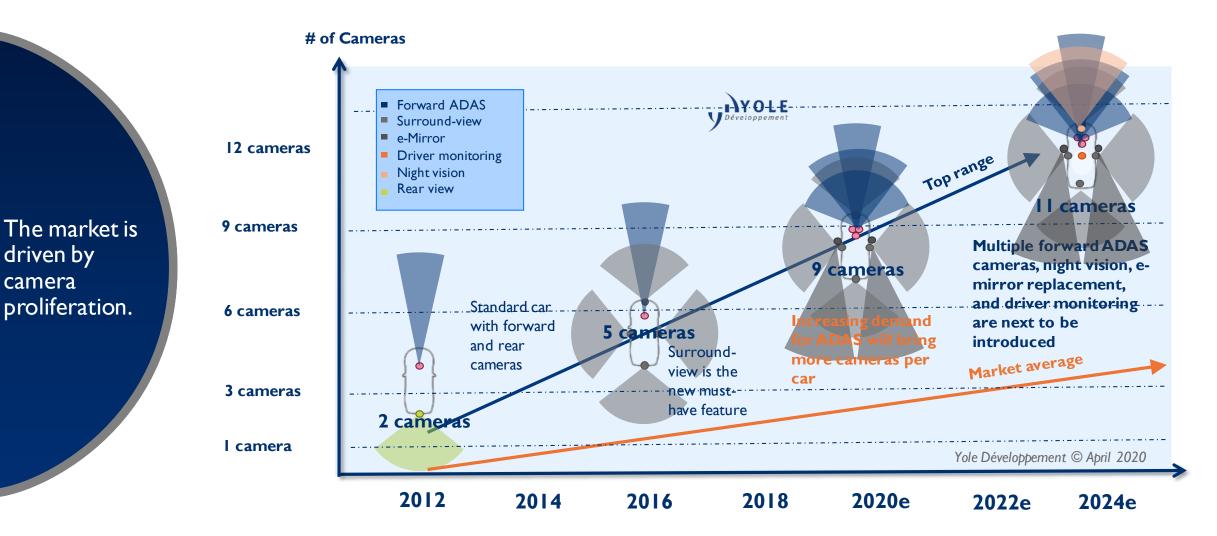
Automotive radar market shares

**Top five** Emerging Furukawa Waymo TungThih Alps Electric Hyundai Mobis √ayı. 0,1% Chery **Electronic** 0,2% 0,1% Vale<sup>0,7%</sup> **Æ 77.11** Ontinental 🏂 0.3% l,8% Nidec 0,0% Panasonic ZF-TRV2,6% 0.0% Mando • A P T I V 6,6% Others 0.0% Nider Aptiv BOSCH -All for dreams 7,5% The top five Invented for life Perfecting the Art of Electronics **Continental** companies 24,7% **DENSOTEN** capture 83% of HYUNDAI MOBIS the market. Veoneer The merging veoneer 8.6% **Panasonic** players are progressing well.Waymo's 2019 **Others Special** \$5,338M market share has started to Valeo = become visible. Denso WAYMO 16,5% 同数電子企業股份有限公司 = (TTE Hella TungThih Electronic Co., Ltd. 14.6% **Bosch** 15,6% = CHERY

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## THE PROLIFERATION OF CAMERA MODULES

The 'Ten-plus cameras per car' roadmap





## CAMERA MODULE MARKET SHARES

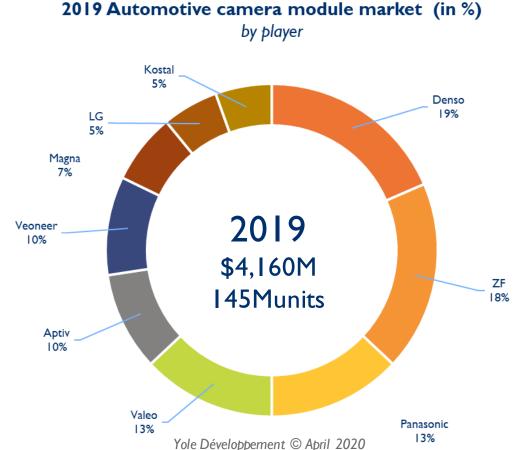
Automotive camera module - Market breakdown by manufacturer in %

Tier-1s have entered the fray and trust the main positions.

The market is still highly competitive, and Tier-Is trust the first positions. All other players are wellknown camera manufacturers that have diversified from either mobile or digital photography.

Competition will probably toughen in the next few years as market growth attracts more players.

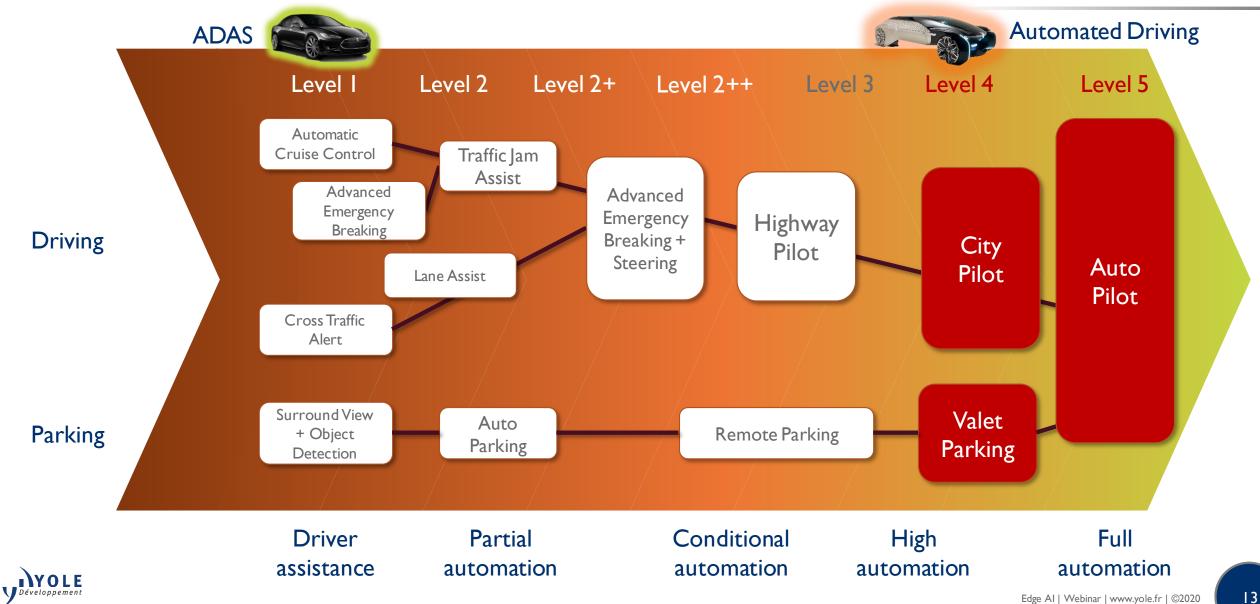






## THE EVOLUTION OF DRIVING

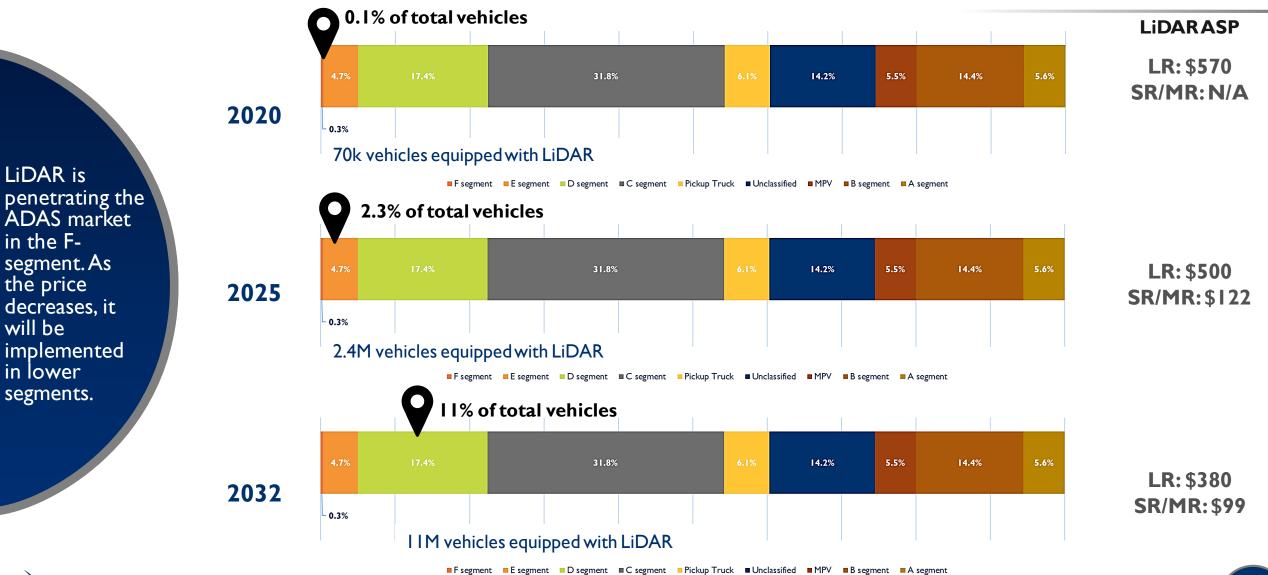
### Evolution of functionalities towards full autonomy



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## THE EMERGENCE OF LIDAR

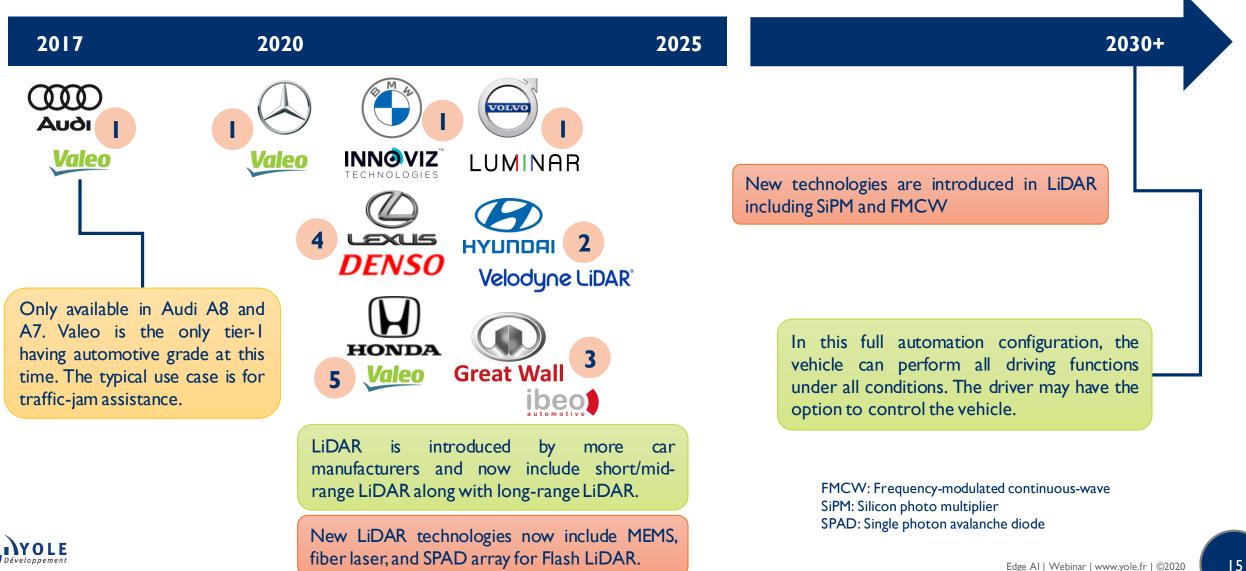
## Adoption of LiDAR in ADAS vehicles





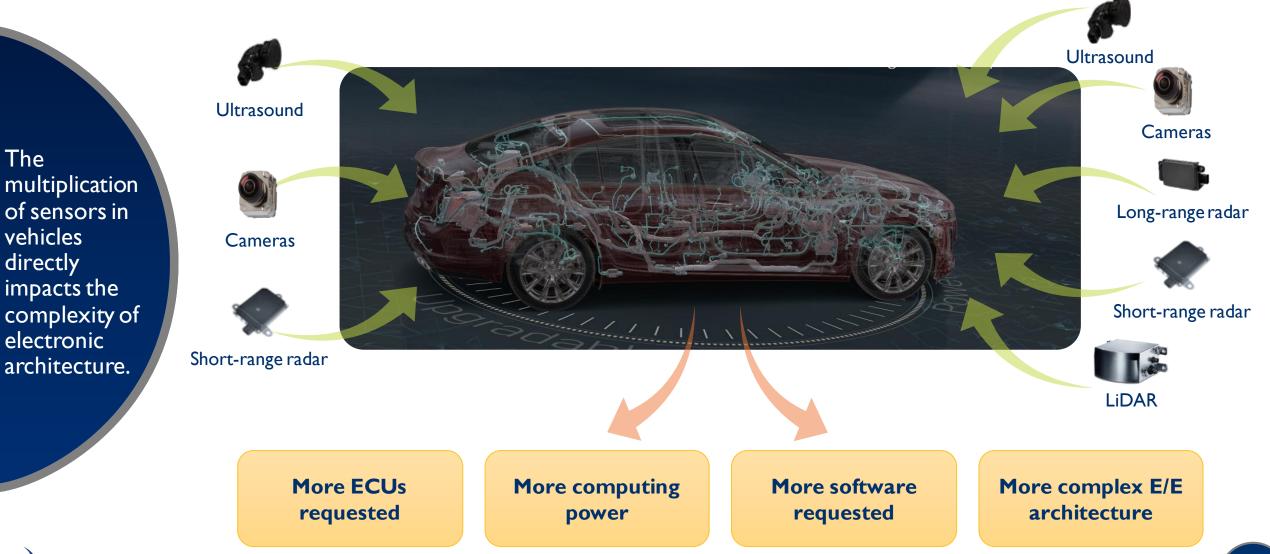
## THE EMERGENCE OF LIDAR

ADAS LiDAR roadmap



## THE ADDITION OF SENSORS

Impact of adding sensors in ADAS vehicles

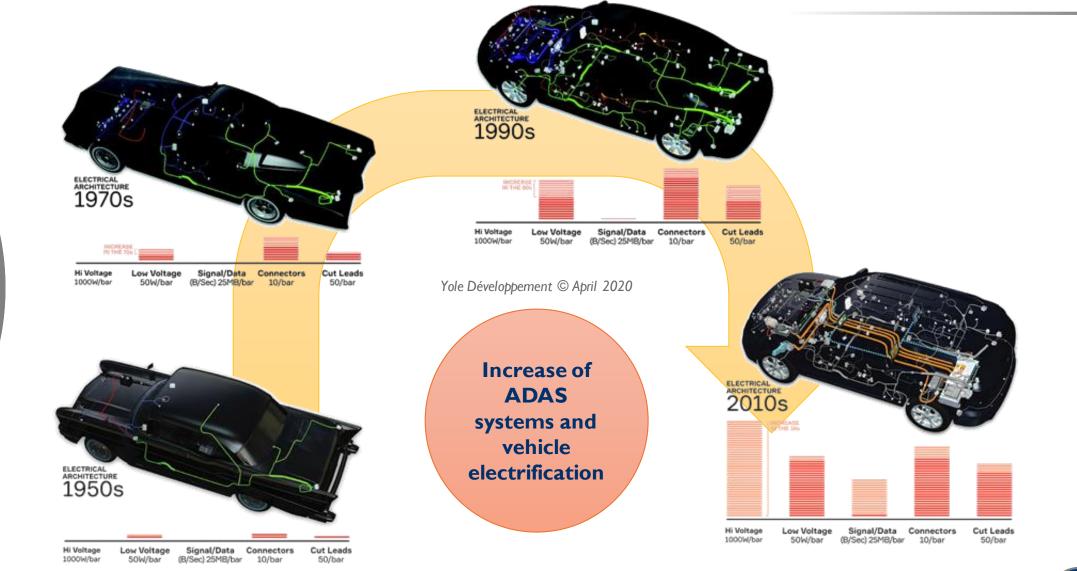




## E/EARCHITECTURE AND COMPUTING

## Evolution of E/E architecture

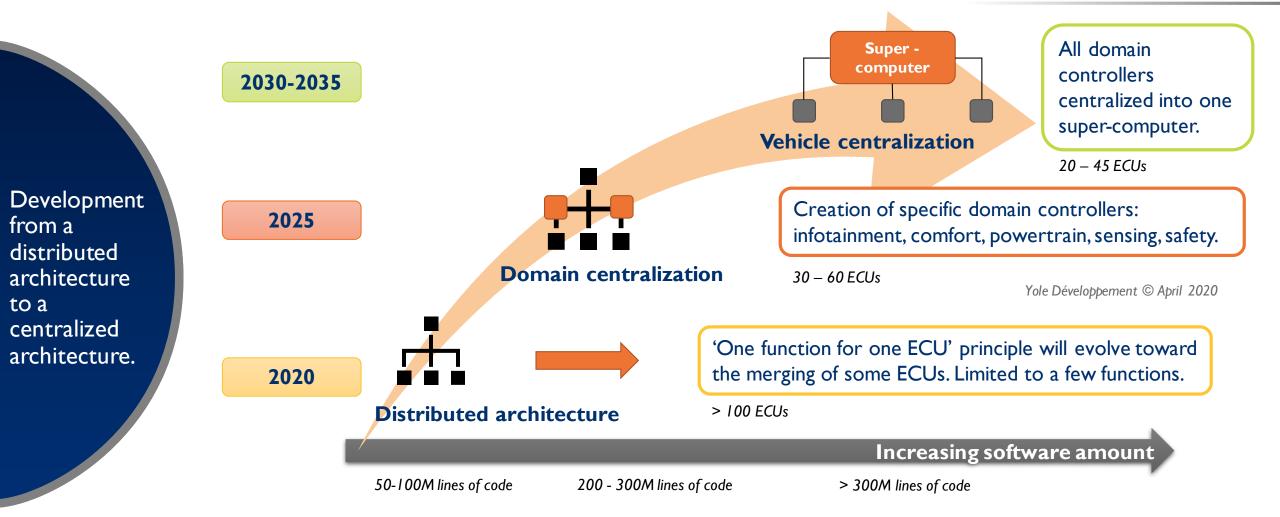
Consumer demand for safety and softwareenabled features is increasing at an unprecedented rate.





## THE TRANSFORMATION OF E/E ARCHITECTURE

E/E architecture evolution - Roadmap



• Today, OEMs are still using a distributed E/E architecture with roughly one ECU per function.

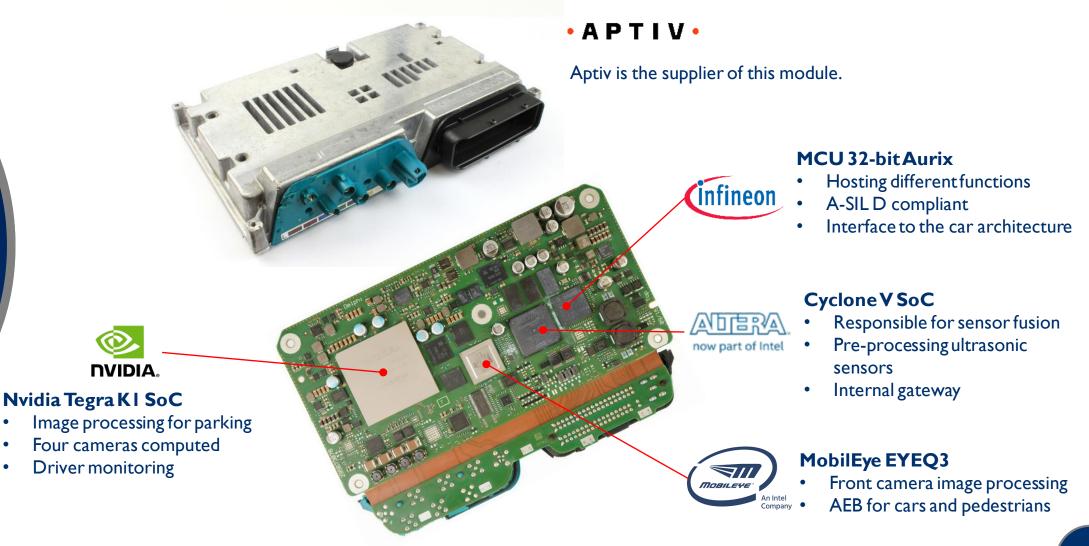


## THE TRANSFORMATION OF E/E ARCHITECTURE

zFAS module from Audi – Teardown from S+C



This module has been developed to integrate data coming from radars, cameras, LiDARs and ultrasonic sensors.

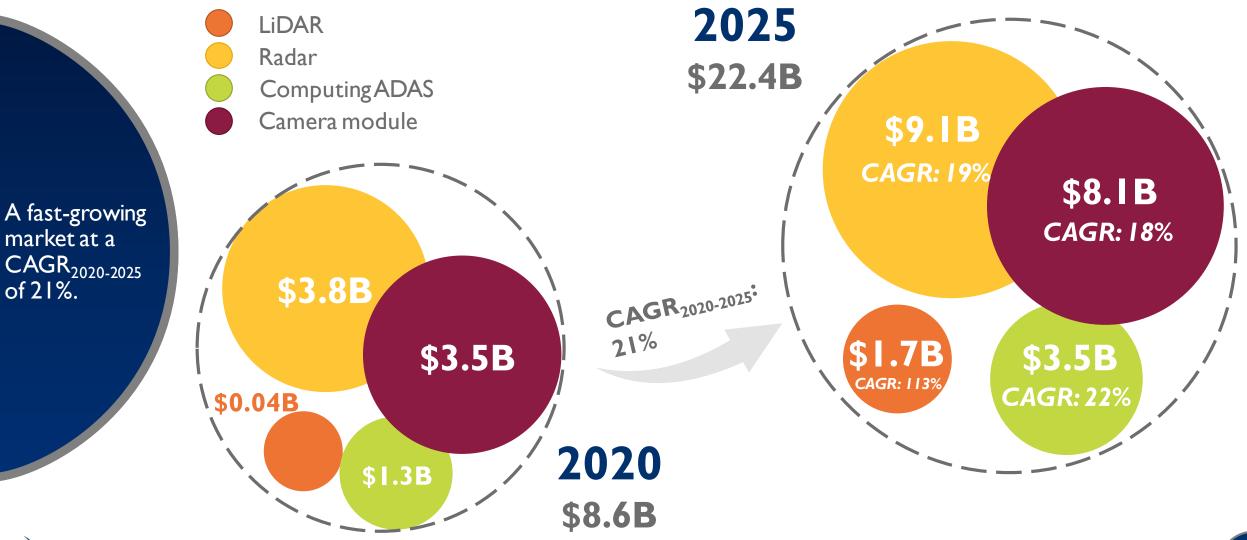




Courtesy of System Plus Consulting

## MARKET FORECASTS

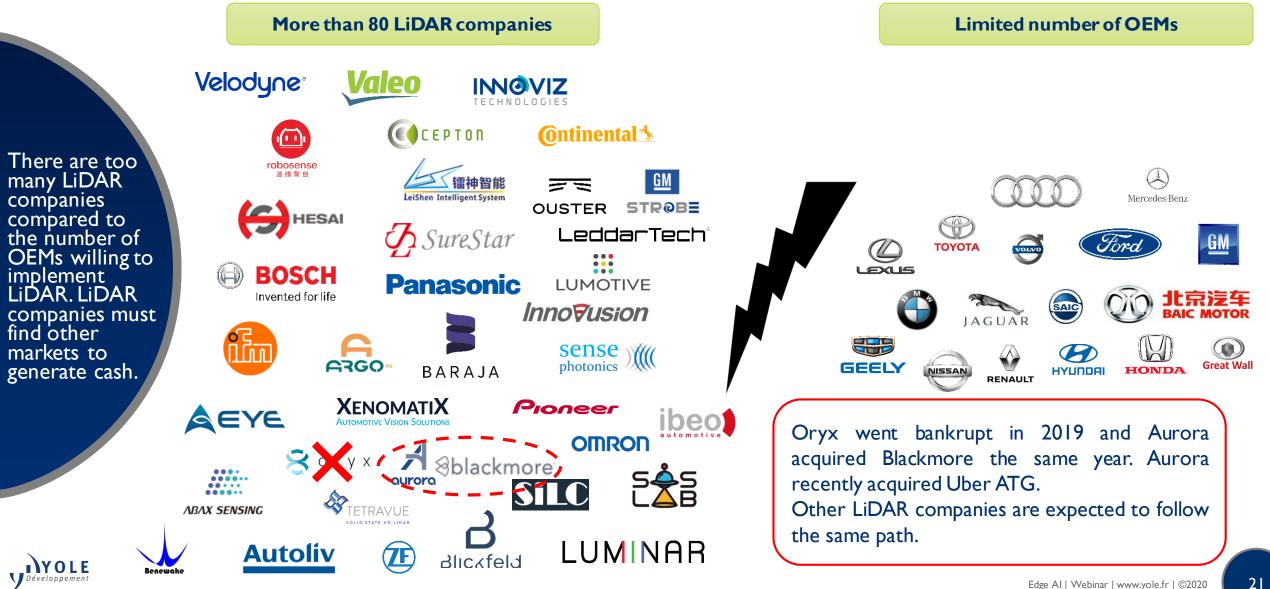
Overview of sensors and computing market revenue





## **INDUSTRY OVERVIEW**

## Consolidation expected in the LiDAR industry



## ROBOTIC VEHICLE SENSING TECHNOLOGY TREND

5<sup>th</sup> generation Waymo sensor suite



Robotic vehicles will primarily use industrial grade technology.

<b>Lidars</b> Short-/mid range Long range	x4 x1
<b>Radars</b> 360° view	<b>x6</b>
<b>Cameras :</b> 360° view Cameras	x29

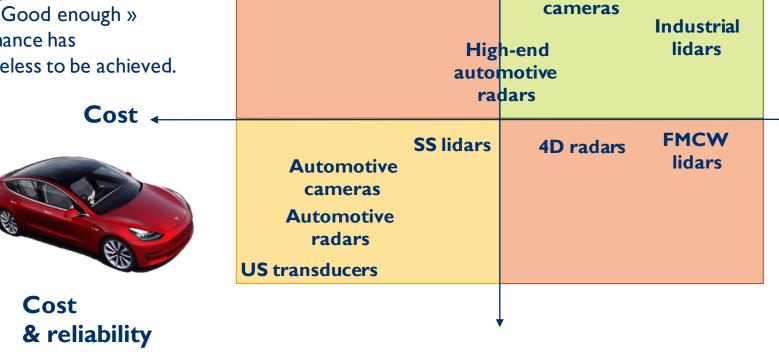




## SENSING FOR AUTONOMOUS DRIVING

Automation Automotive /Aerospace

For ADAS equipment, cost is the primary driver and reliability the barrier to entry. « Good enough » performance has nevertheless to be achieved.



#### **Market Drivers**

#### **Serviceability**

Reliability

"Lidars have been instrumental in putting

fully self-driving cars on public roads"

Industrial



#### Performance & supportability



#### Performance

Robotic vehicles are using highend industrial sensors. The retrofit approach and the serviceability/low volume of MaaS means there is no stringent reliability nor cost issue. The key driver here is performance.



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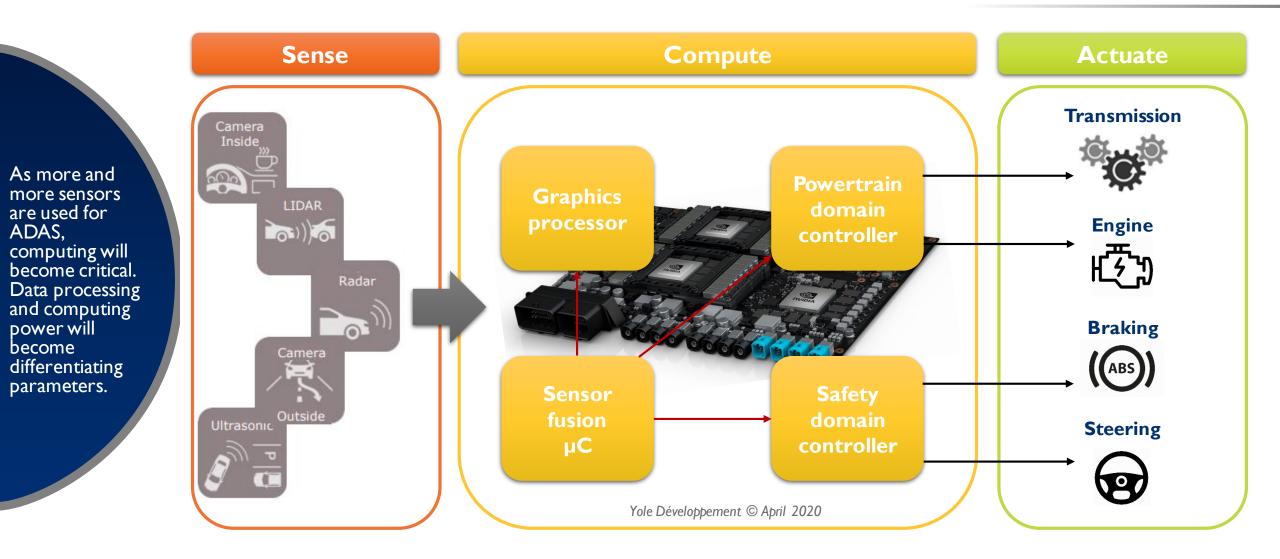
## LOGISTICS: THE FLOW OF THINGS



## LOGISTICS: MANY PLAYERS ALREADY INVOLVED



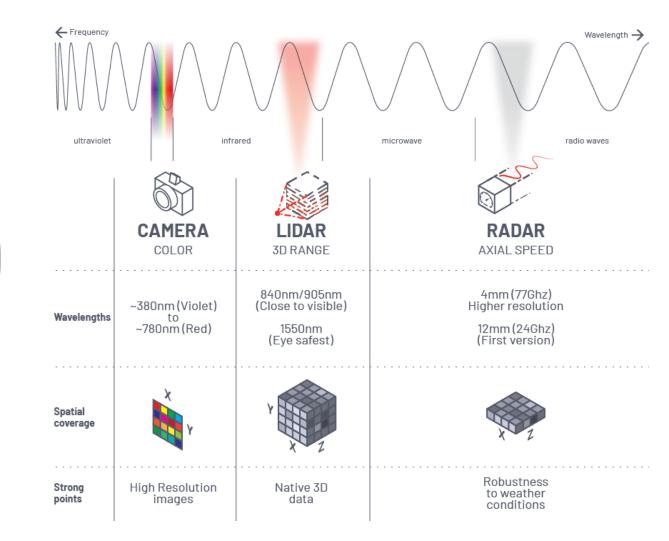
## Computing unit – ADAS system overview





## Different sensor capabilities for sensor fusion

There is no perfect 3D sensing technology.



**<u>Camera</u>**: provide high resolution images but lack of native depth information and depend on light conditions.

**<u>Radar</u>**: measure velocity with great precision but have trouble to detect static objects and to measure the position of objects due to low resolution.

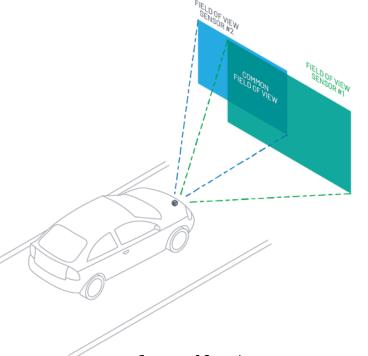
**LiDAR**: only sensor to provide native 3D data but high performances LiDAR are very expensive.



Courtesy of Outsight

## The parallax issue

Calibration will be crucial to combine different perspectives.



Courtesy of Outsight

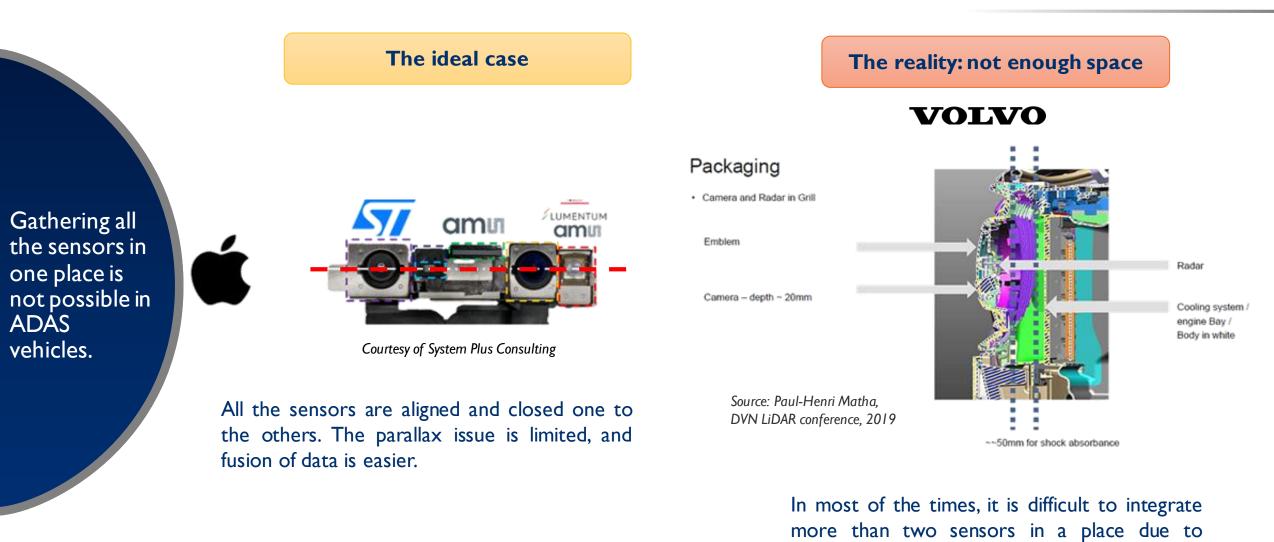
When sensors are positioned apart from each other, they will have a different perspective on the vehicle's environment (parallax) which may lead to a situation in which one sensor can perceive an object, while it is occluded for the other sensor







## Dream vs reality



several constraints.

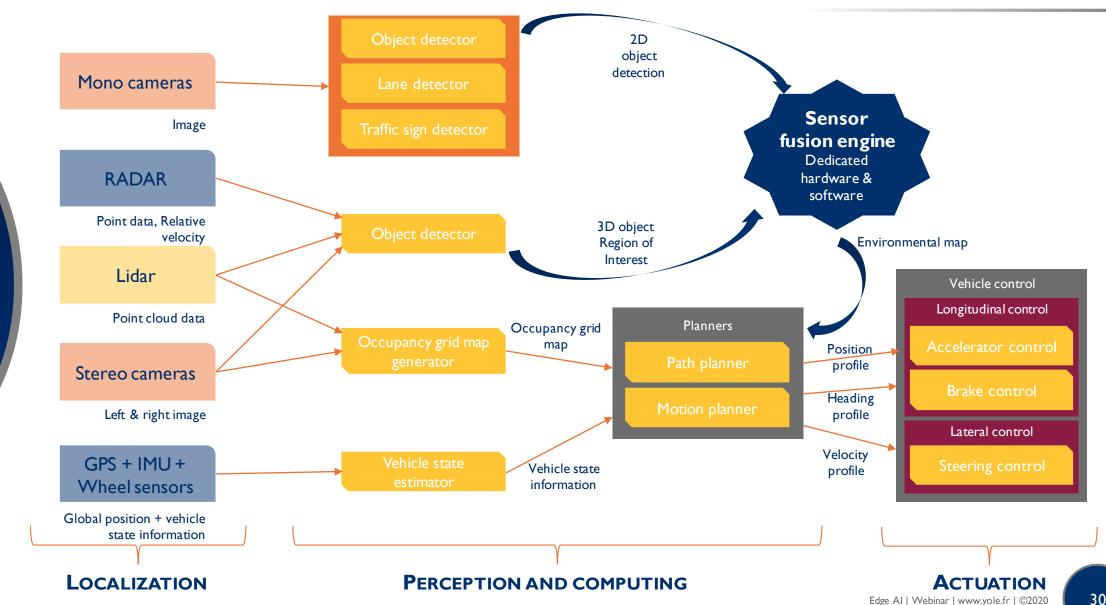
## The place of the sensor fusion engine in the control decision map

Sensor fusion uses sophisticated computer vision and deeplearning-based algorithms

Complex usecase scenarios expected of driverless cars can be understood.

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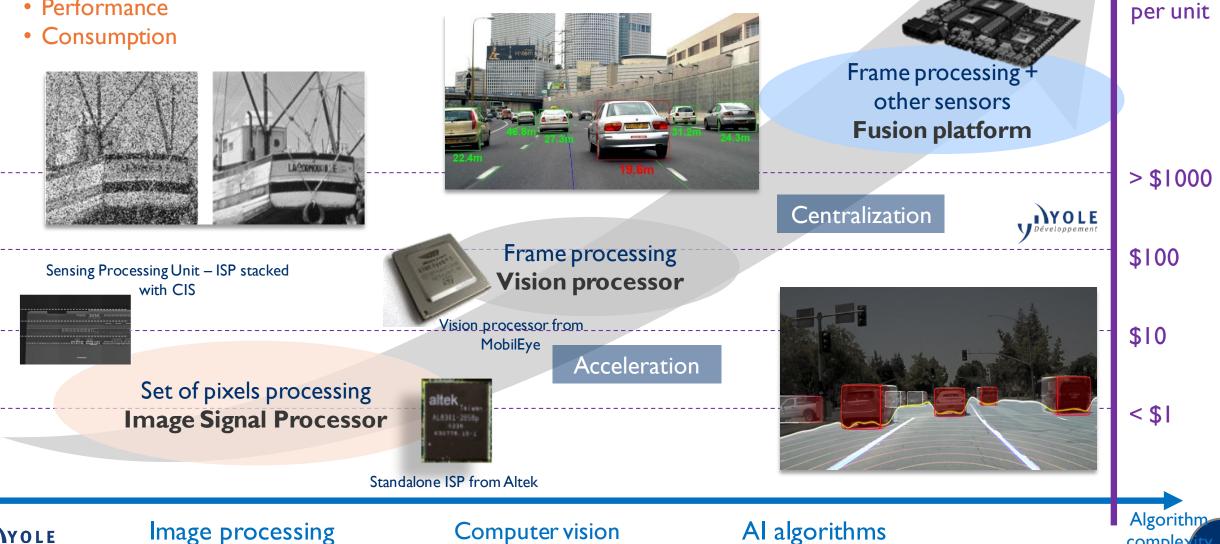


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From image processing to fusion platform

- Amount of data processed
- Performance

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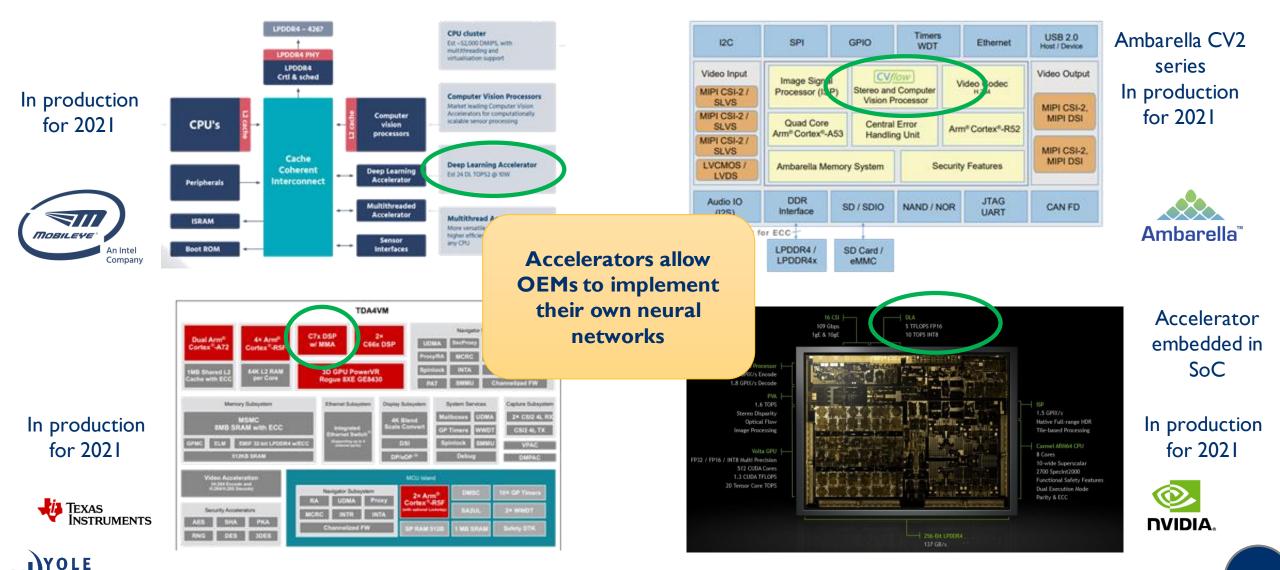


Price

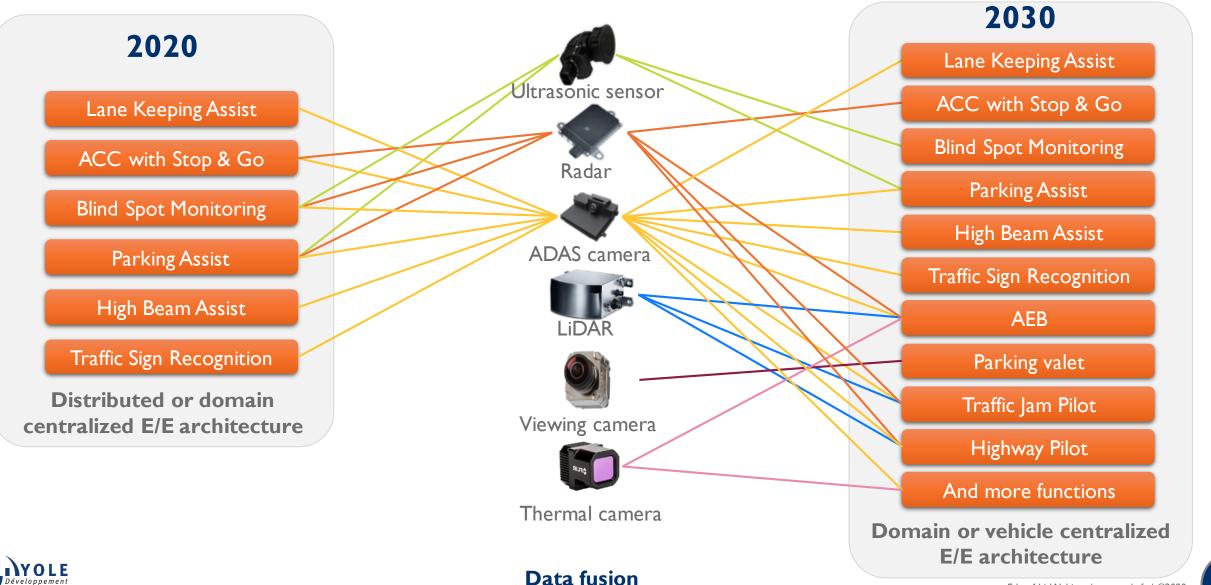
Fusion platform from NVIDIA

Développemen

## Toward accelerators in automotive



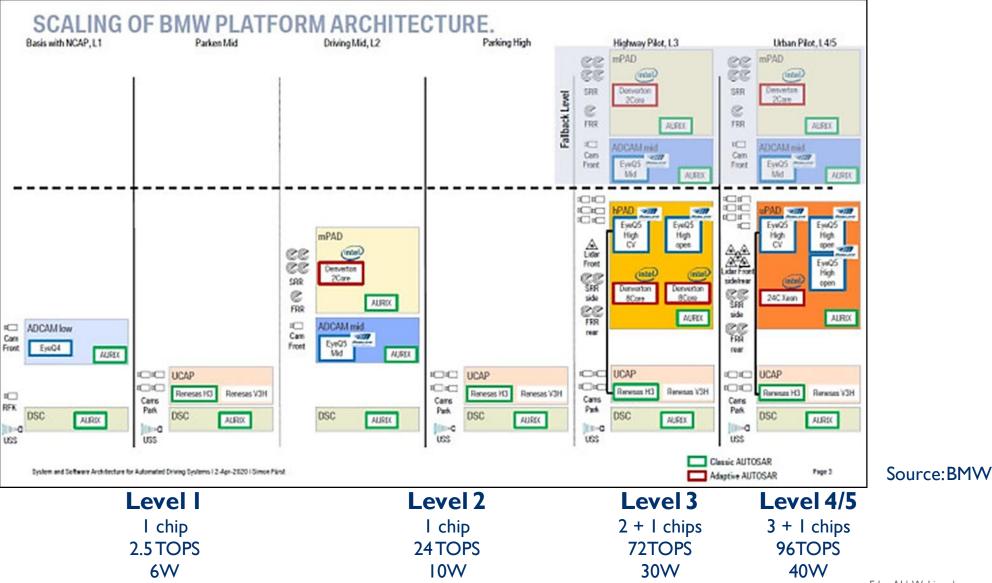
Data fusion for automated driving enables more functionalities



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**Développement** 

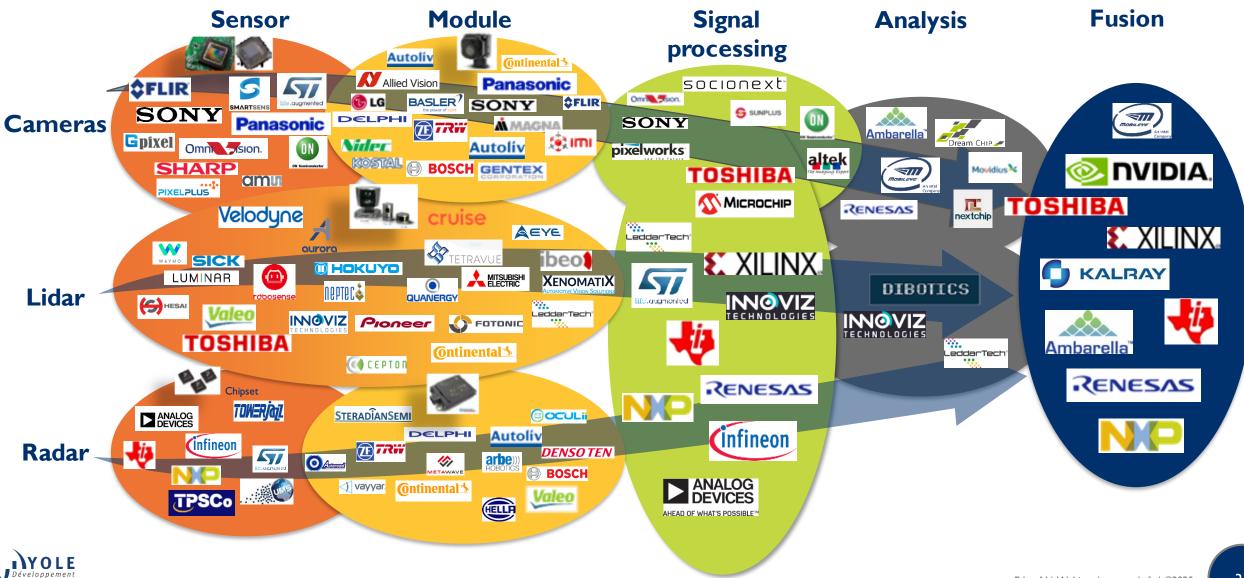
## Add chips to add functionalities



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From sensors to fusion in automotive – Overview of players



## From Technologies to Markets

# Thank you for your attention

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