

AKIDA™ Event-Domain Neural Processor

Ultra Low-Power Edge AI Solutions

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- ★ Event-based Architecture advantage of AKIDA[™] technology
- ★ First Brainchip product based on AKIDA[™] technology
 - * **AKD1000** Neural System On Chip (NSoC)
- **★ Example Neural Networks optimized to run on AKIDA**[™]
- * Discussion

The Challenges of Edge Computing

- * AI at the Edge, computing requirements require a different solution:
 - * Balance an extremely low power budget with real-time performance
 - * Operate within severe constraints on memory capacity and bandwidth
 - * Off-load tasks from the (limited) CPU
 - * Real-time learning or rapid retraining at the edge
- * AKIDA[™] overcomes these challenges by adopting a Neuromorphic Architecture.
 - * Neuromorphic processing: event-based processing only consumes power when an event occurs
 - * Run the Al inference by running it in event domain
 - * Reduced memory requirement, 1, 2 or up to 4 bits for weights and activations
 - * **On-chip learning in event domain,** using BrainChip's proprietary algorithms



BrainChip's AKIDA[™] Neuromorphic Design Principles

* Distributed Computation

- Computation spread across many cores (<u>neural processing units</u> <u>NPUs</u>)
- * Each NPU has its own dedicated computational engine and memory, which reduces data movement

* Event-Based Processing

- * Non-zero activation map values are represented as multi-bit (1 to 4-bit) events
- * NPUs only perform computation on events, not activation maps

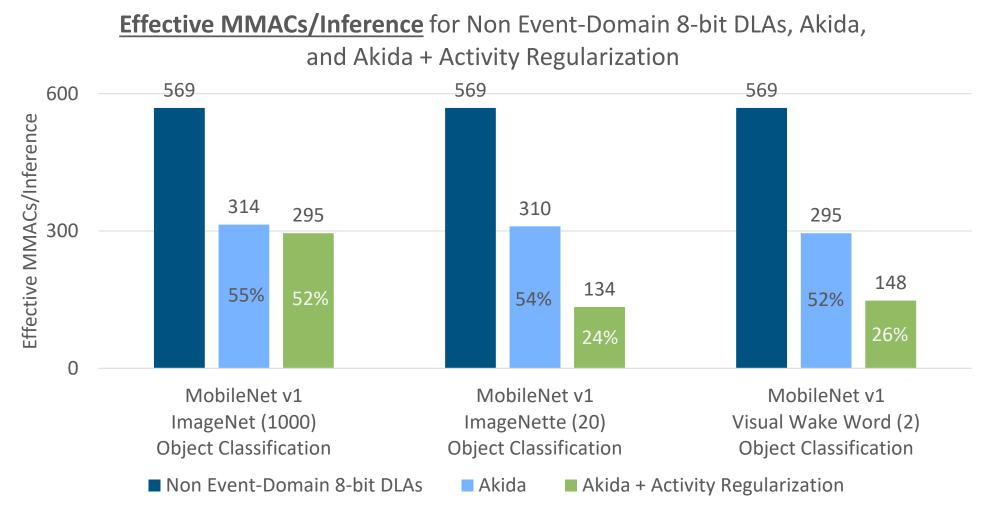
* Event-Based Communication

- * NPUs communicate by sending events to each other over a mesh network without host CPU intervention
- * Neural network connectivity is configurable in the field

* Event-Based Learning

- * AKIDA implements an on-chip, learning algorithm
- * No costly communication with cloud required

Operation Reduction Effect of Event-Based Processing



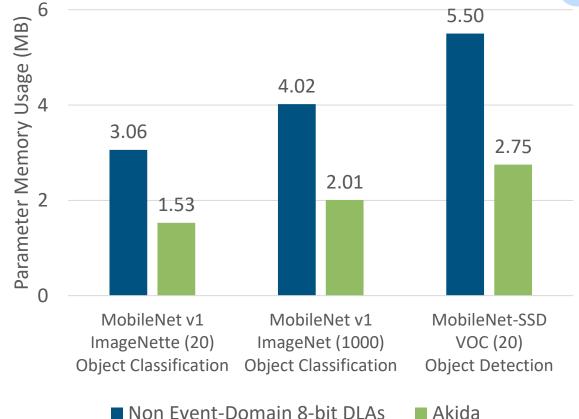
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AKIDA[™] Utilizes Low-Bit Precision to Reduce Memory/Bandwidth

- Akida uses 1-4 bits for activations and parameters
 - 50% (or greater) reduction in memory & bandwidth compared to 8-bit hardware
- We currently perform quantization-aware training to preserve accuracy
- Multiple research groups preserve accuracy with post-training 4-bit quantization*

*Banner, R., et al (2019) Advances in NIPS

Parameter Memory Usage (MB) for Non Event-Domain 8-bit DLAs and Akida



https://www.technologyreview.com/2020/12/11/1014102/ai-trains-on-4-bit-computers/

Selected BrainChip Quantization Results

Model	Dataset	# Classes	Weight/Activation Quantization	Quantized Accuracy	32-Bit Float Accuracy
DS-CNN 47K parameters	Google Speech Commands	33	4/4	91.9%	93.4%
MobileNet 224 0.25 200K parameters	Visual Wake Word	2	4/4	89.7%	90.7%
MobileNet V1 2.7M parameters	CIFAR10	10	4/4	93.1%	93.5%
MobileNet V1 4.2M parameters	ImageNet 1000	1000	4/4	68.8%	71.4%
MobileNet SSD 300 5.8M parameters	VOC	20	4/4	65.4%	66.9%
VGG 14.0M parameters	CIFAR10	10	2/2	90.7%	93.2%

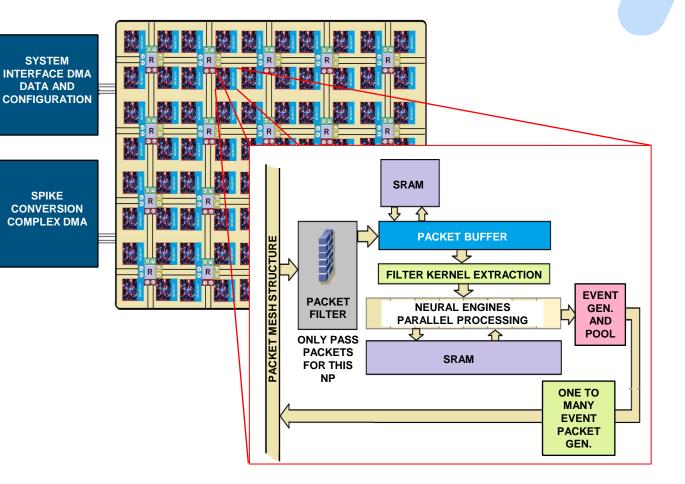
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Performance for Small Models on Akida

Data Input Type	Model	Data Set	Num Class	Act. Spars. %	Number of Parameters	Required Parameter Memory	Clock (MHz)	FPS	Top-1 Acc. %
RGB Images	MobileNet v1 α=0.25 R224	Visual Wake Word	2	33	210.4 k	102.7 kB	127.84	10.0	89.7
Spatiotemporal 3D Point Cloud	BRN Hand Gesture CNN (4a/2w Mixed Prec.)	Custom DVS Hand Gesture	N/A	>90	1.7 M	418.3 kB	10.10	10.0	N/A
Spatial 3D Point Cloud	BRN MagikEye CNN	Custom MagikEye Hand Gesture	9	91	283.4 k	138.4 kB	7.49	10.0	~90
Audio MFCC	DS-CNNs	Google Speech Commands	33	61	47.2 k	26.6 kB	3.96	10.0	91.9
Resistance Time-Series	Fox 3000 Olfactory ANN	Fox 3000 Olfaction	20	0	138.2 M	16.4 MB**	0.68	10.1	98.2
Accelerometer Time-Series	BRN Custom Bearing Fault Detection CNN	CWRU Bearing Fault Detection	10	50*	139.8 k	68.3 KB	5.53	10	90.0

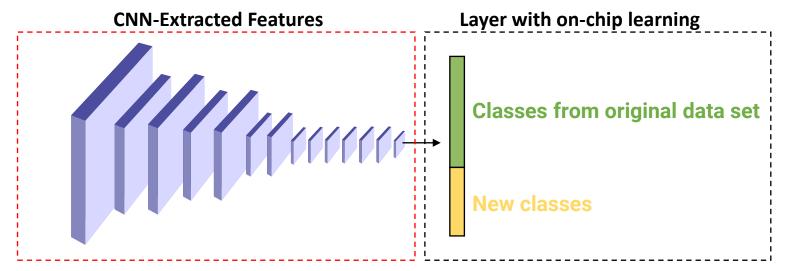
BrainChip's AKIDA[™] NPU Architecture and IP solution

- * NPUs communicate via a mesh network
- Layers distributed across multiple NPUs
- * Each NPU has:
 - * 100 KB of local SRAM for:
 - * Parameters and activations
 - * Internal event buffers
 - * Eight compute engines running in parallel
 - Input event packet processing
 - Output event generation
 - * Dedicated learning hardware
- Each NPU can be configured to process
 - * 2D convolutional layers
 - Dense layers



Edge Learning with AKIDA[™] On-Chip Learning

- 1. Train CNN feature extractor offline on original dataset
- 2. Replace last classifier layer with Akida layer capable of on-chip learning
- 3. Perform few-shot learning: learn from a few samples
 - a) original classes (green)
 - b) new classes (yellow) should share similar features with original classes



- We have demonstrated edge learning for:
 - Object detection using MobileNet trained on the ImageNet dataset
 - Keyword spotting using DS-CNN trained on the Google Speech Commands dataset
 - Hand gesture classification using small CNN trained on a custom DVS events dataset

AKIDA[™] Software Development Environment (ADE) and Training Workflow

Akida Software Development Stack

Akida[™] Chip Simulator pip install akida

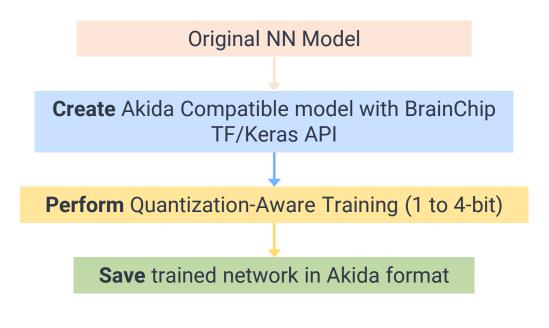
Training tool (CNN2SNN)

pip install cnn2snn

Models pip install akida-models

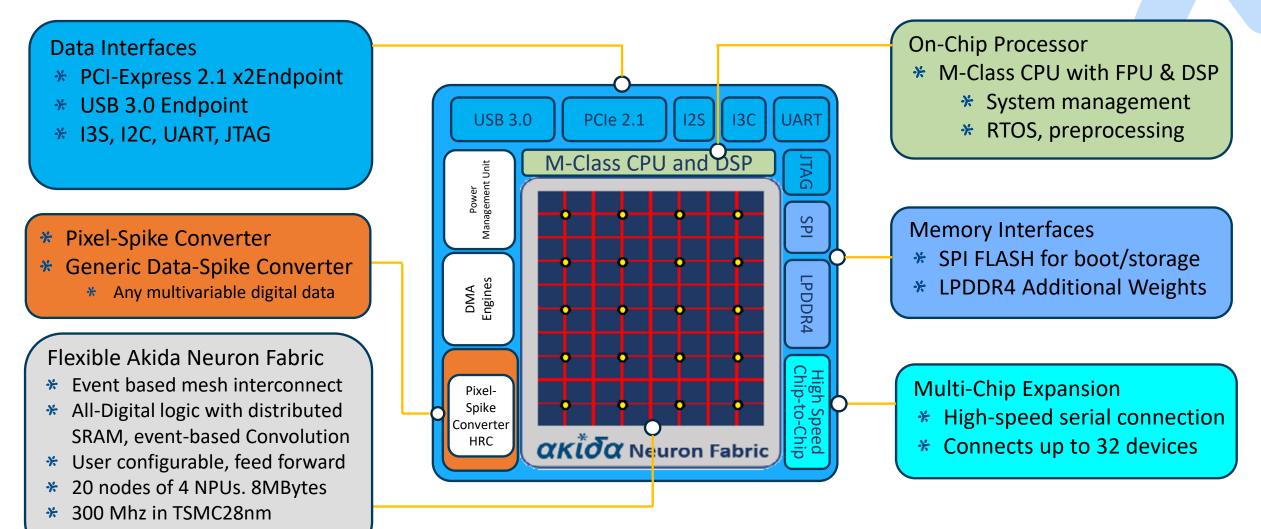


CNN2SNN Training Tool Workflow

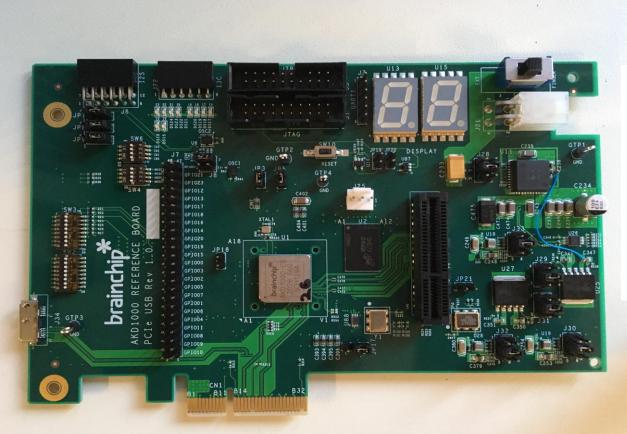


https://doc.brainchipinc.com/

AKIDA[™] Based AKD1000 NSoC Chip Block diagram



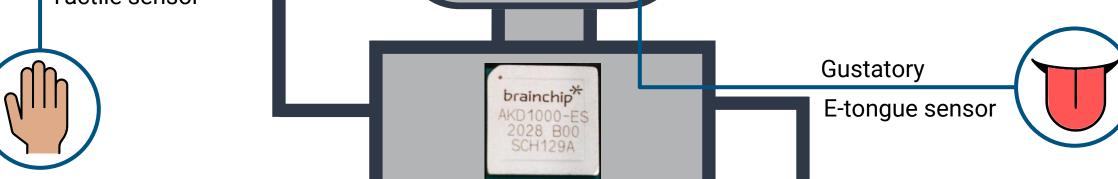
AKD1000 based PCIe Plug in CARD





Akida Applications

AKIDA[™] Enables Efficient Processing of All Sensor Modalities Visual Image Sensor Auditory Microphone Olfactory Somatosensory E-nose sensor Accelerometer Tactile sensor



Keyword Spotting: Always on Listening to Microphone

- Google Speech Commands Data Set*
 - 65k 1-second long audio clips of 30 keywords
 - ✤ Each keyword has ~1,500 4,000 samples
 - Data set is split into training/validation/testing in an 80/10/10 ratio

- Class structure 12 classes
 - * 10 classes for 10/30 words
 - * 1 class for silence
 - 1 class for 'unknown word' that represents the other 20/30 words

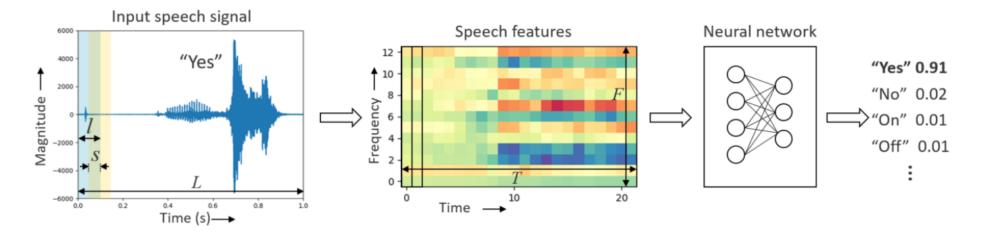


Figure 1: Keyword spotting pipeline.*

* Warden, Pete. 2018. ArXiv:1804.03209 [Cs], http://arxiv.org/abs/1804.03209.

** Zhang, Yundong, Naveen Suda, Liangzhen Lai, and Vikas Chandra. 2018. ArXiv:1711.07128 [Cs, Eess]. http://arxiv.org/abs/1711.07128.

Keyword Spotting Network on AKIDA[™] Chip: See Live Demo

* KWS Network

- * DS-CNN with 8 layers (4-bit act./wt.)
- 47k parameters
- ✤ 7 NPUs and ~55 kB of SRAM

✤ Results

- Top-1 Accuracy
 - Floating point: 93.4%
 - * 4-bit/4-bit weights/activations: 91.9%
 - Speed: 10 FPS and 100 ms latency
 - Activation Sparsity: 61%
 - Dynamic Power: 167 μW
 - Efficiency: 16.7 µJ/Inference

DS-CNN

Layer	Output Dim
Input	49x10x1
Conv MP 5x5	25x5x32
DWS Conv 3x3	25x5x64
GAP	1x1x64
DWS Conv 3x3	1x1x256
Dense	1x1x33

Total Params = 47,232

Person Detection: Always on Camera Input

- * Visual Wake Word Data Set*
 - Person detection data set
 - Generated from COCO 2014 data set
 - * 115k images for training and validation

Some Example Images from the COCO training set*



- Class structure 2 classes
 - Person class
 - Not-Person class

Person

Not-Person

Visual Wake Word and MobileNet 0.25 on AKIDA[™] Simulator

* Person Detection Model

- MobileNet v1 0.25 at 96x96x3 (4-bit act./wt.)
- * 210k parameters
- * 14 NPUs and ~178 kB of SRAM

✤ Results

- * Top-1 Accuracy
 - ✤ Floating point: ~76%
 - * 4-bit/4-bit weights/activations: 75.9%
- Speed: 10 FPS and 100 ms latency
- Activation Sparsity: 32%
- Dynamic Power: 1.5 mW

MobileNet 0.25 at 96x96x3

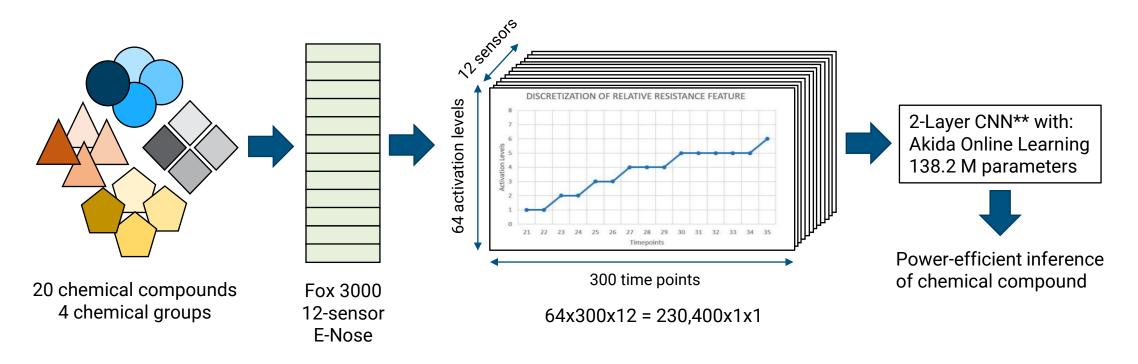
Layer	Output Dims	Filter Dims Stride	Number of Repeated Layers
Input	96x96x3	N/A	1
Conv 2D	48x48x8	3x3x3/2	1
DW Conv 2D	48x48x16	3x3x3/1	1
DW Conv 2D MP	24x24x32	3x3x3/2	1
DW Conv 2D	24x24x32	3x3x3/1	1
DW Conv 2D MP	12x12x64	3x3x3/2	1
DW Conv 2D	12x12x64	3x3x3/1	1
DW Conv 2D MP	6x6x128	3x3x3/2	1
DW Conv 2D	6x6x128	3x3x3/1	5
DW Conv 2D MP	3x3x256	3x3x3/2	1
DW Conv 2D	3x3x256	3x3x3/1	1
GAP	1x1x256	3x3x1/N/A	1
Fully	1x1x2	1x1x256/N/A	1

Total Params = 210,416

Fox 3000 E-Nose Olfactory Classification

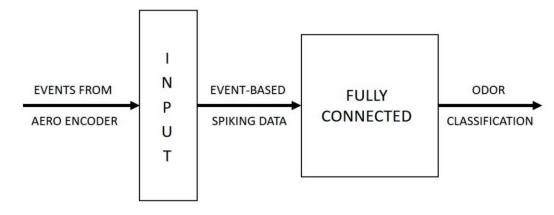
- * Fox 3000 Olfactory Data Set*
 - 20 chemical compounds
 - * 10 samples per compound

- Each sample is 300 time points
- * 150 sec sampled at 2 Hz



Fox 3000 E-Nose Olfactory Classification

- * Training on Fox 3000 Olfactory data set*
 - * 2-layer CNN with:
 - 1-bit weights
 - * 1-bit activations
 - Single input layer connected to fully connected layer
 - Trained with Akida learning rule



20-Class 2-Layer CNN

Layer	Output Dim
Input	230,400x1x1
Dense	600x1x1

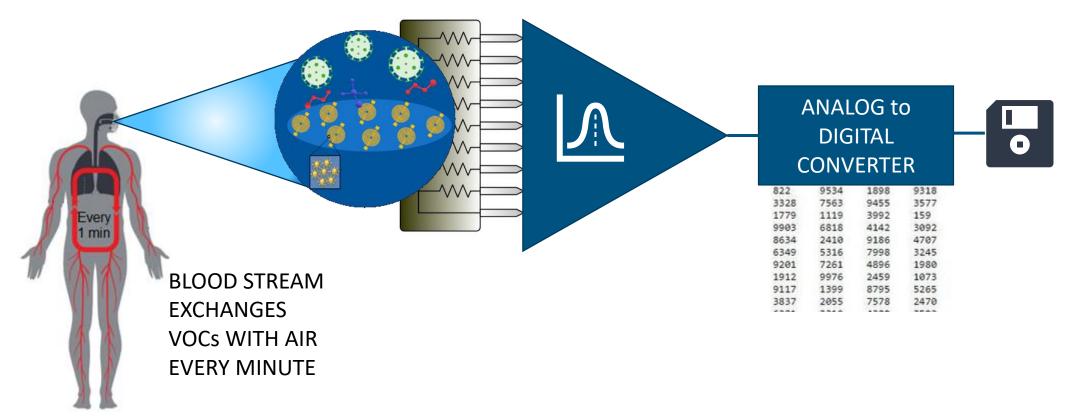
Total Params = 138.2 M

20-Class Results**

- * 98.2% Top-1 accuracy
- * 1 NPU/16.5 MB Ext. RAM *
- * 10 FPS/100 ms latency
- Dynamic power: 7.0 mW
- Clock Freq: 43.2 MHz
- Batch Size = 1

COVID-19 and Akida, Collection Method

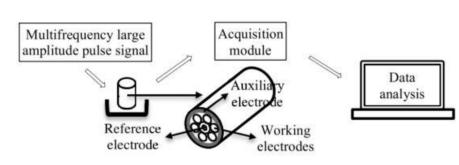
EXHALED BREATH -> MONOLAYER-CAPPED GNP SENSORS-> OPAMP -> ANALOG TO DIGITAL CONVERTER -> STORAGE



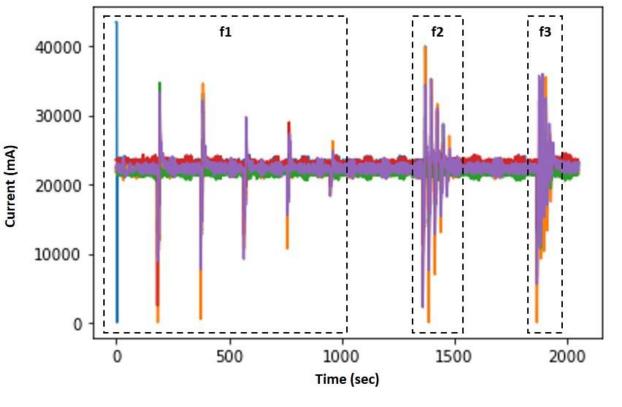
ACS Nano 2020, 14, 9, 12125-12132 Multiplexed Nanomaterial-Based Sensor Array for Detection of COVID-19 in Exhaled Breath

Taste Classification with E-Tongue Systems

- Voltammetry obtains information about a sample by measuring the current as the potential is varied
- Data set* composed of a series of pulse voltammetry waveforms
- * Pulse signals comprised of:
 - * Three frequencies
 - * Five voltage amplitudes



Electrochemical Cell Response for Black Tea Sample



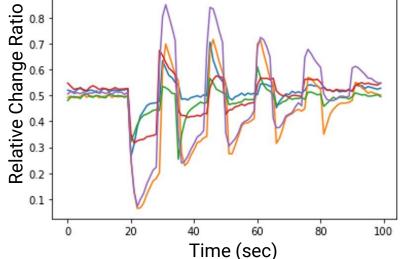
Framework* for e-nose system

* Adapted from Zhang et al. IEEE transactions on cybernetics, vol. 49, no. 3, pp. 947-960, 2018.

Taste Classification with E-Tongue Systems

- * E-Tongue Classification Data Set*
 - * 114 measurements from five electrodes
 - * 13 types of liquid samples
 - * Each sample had 500 elements
 - Five sensors
 - 100 time-points per sensor
- Training
 - Trained with Akida learning rule
 - Train/test split: 70%/30% samples
- Results
 - * 95.8% Top-1 accuracy
 - * 4 NPUs/254 KB Ext RAM
- * 10 FPS and 100 ms latency
- Dynamic power = 1.1 mW

E-Tongue Data Sample Example



BrainChip 2-Layer ANN

Layer	Output Dim
Input	100x16x5
Dense	1x1x260

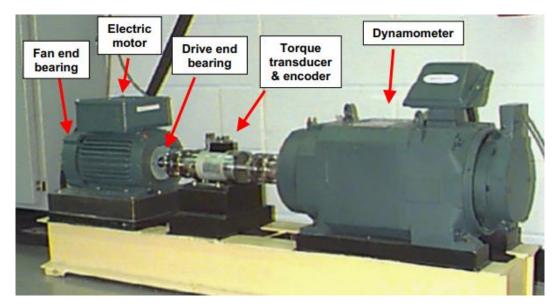
Total Params = 2.1 M 1-bit weights/activations

Batch Size= 1

* Zhang et al. IEEE transactions on cybernetics, vol. 49, no. 3, pp. 947-960, 2018.

Electric Motor Ball Bearing Fault Diagnosis

- Condition-based maintenance (CBM):
 - * Perform maintenance only when necessary
- * This study focuses on <u>diagnosis</u>
- Motor bearings were seeded with faults
- Accelerometer data taken at locations near to and remote from the motor bearings



Taken from CWRU Bearing Data Center Website*



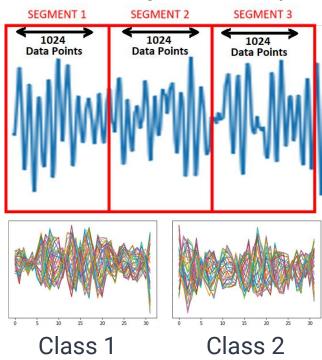
- * There were three different fault types
 - Ball defect
 - Inner race fault
 - * Outer race fault 🚽 🛛 *
- Each fault came in 3 sizes for a total of
 - 9 faulty classes
 - * 1 normal class

*CWRU Bearing Data Center Website: https://csegroups.case.edu/bearingdatacenter/pages/welcome-case-western-reserve-university-bearing-data-center-website

Ball Bearing Fault Detection

- * Ball Bearing Data Set*
 - * Accelerometer data collected at 48 kHz
 - * 10 classes with 460 samples/class
 - * Each sample had 1,024 elements
 - About 10 seconds of data per class
- Training
 - 6-layer CNN with 4-bit weights/ activations trained with back prop.
 - * Train/test split: 3,600/1,000 samples
- Results
 - * 99% Top-1 accuracy
 - ✤ ~50% activation sparsity

CWRU Bearing Data Example



BrainChip 6-Layer CNN

32x32x1
32x32x32
16x16x32
8x8x64
4x4x64
4x4x128
1x1x128
1x1x10

Total Params = 140,448

- Dynamic power = 896 μW
- Batch Size= 1

*CWRU Bearing Data Center Website: https://csegroups.case.edu/bearingdatacenter/pages/welcome-case-western-reserve-university-bearing-data-center-website

5 NPUs and 195 KB SRAM

10 FPS and 100 ms latency

*



- * Run inference in ½ GOPS, ½ memory, and ½ memory bandwidth
- * 3 to 4 times lower power at same clock rate
- * Runtime software manages all configuration and network loading
 - * Application-level API similar to Tensor-flow/Keras
- * Incremental on-chip learning from few samples
- * Available as a chip AKD1000 or Embedded IP in your SoC

Questions



www.brainchip.com @brainchip_inc

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