



Advancing AI Processing Architecture for a New Era of Intelligent Vehicles

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Automotive BU, Horizon Robotics

January 2021



Agenda

- Horizon Robotics
- Perception Compute Platform, AI Algorithms, Processors and Toolchain
- MAPS (Mean Accuracy-guaranteed Processing Speed)



July 2015
founded



1,000+
employees



700+
patents

One of the world's leading **edge AI computing** companies.
Focused on **Smart Mobility**
Processors & solutions **optimized for deep learning**

Our mission: *“Establish the leading AI platform to make human life **safer** and **better**.”*

China's First Auto-grade Processor



In production



Sampling now

Perception Compute System



In production

Matrix

Leading Partners



SAIC MOTOR



clarion



CHANGAN



Global Recognitions



2020 Vision Product of the Year Award
Best Automotive Solution: **Horizon Robotics Journey 2.0 AI Processor**



2020 Tech.AD Runner-up
Most Outstanding Autonomous Vehicle Technology Innovation of the Year Award: **Horizon Matrix 2**



2019 Vision Product of the Year Award
Best Automotive Solution: **Horizon Robotics, Horizon Matrix**



2019 CES Innovation Award

Matrix won the CES Innovation Award in 2019 alongside Nvidia and Waymo

Global Deployment



Horizon Global Business Success



6 CY2020
Model launches

4 models for **Intelligent Cockpit**
2 models for **L2+ ADAS**



40 Design-in
Contracts

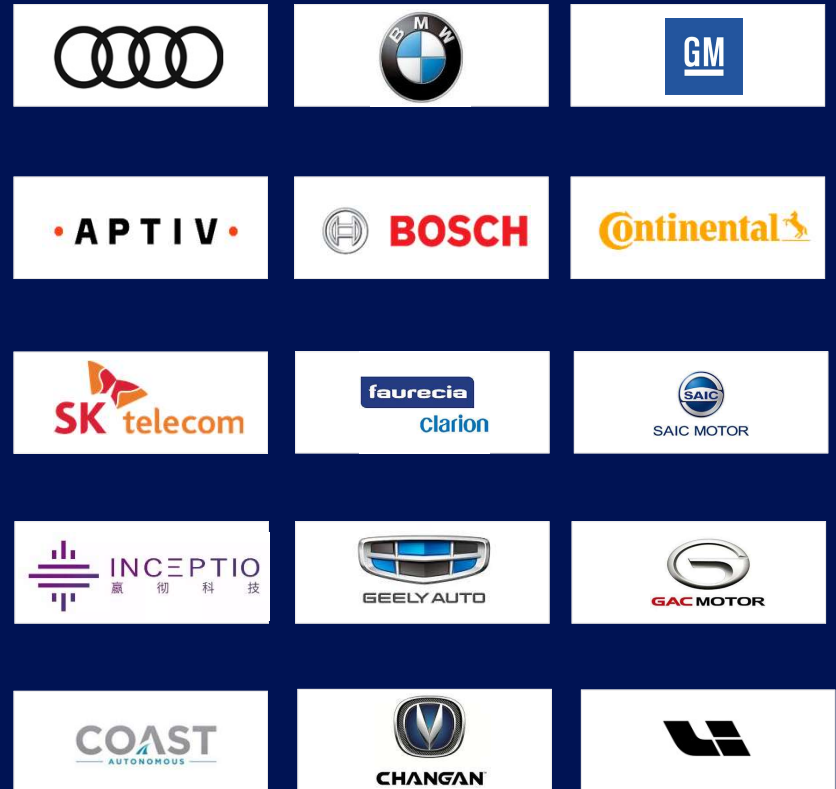
Global OEM/Tier1s customers
150k+ shipment mark in 2020



60+ Ongoing
Projects

Increasing momentum in
ADAS, Automated driving,
Robotics mobility and
intelligent cabin

Growing Partnerships



+ More ongoing

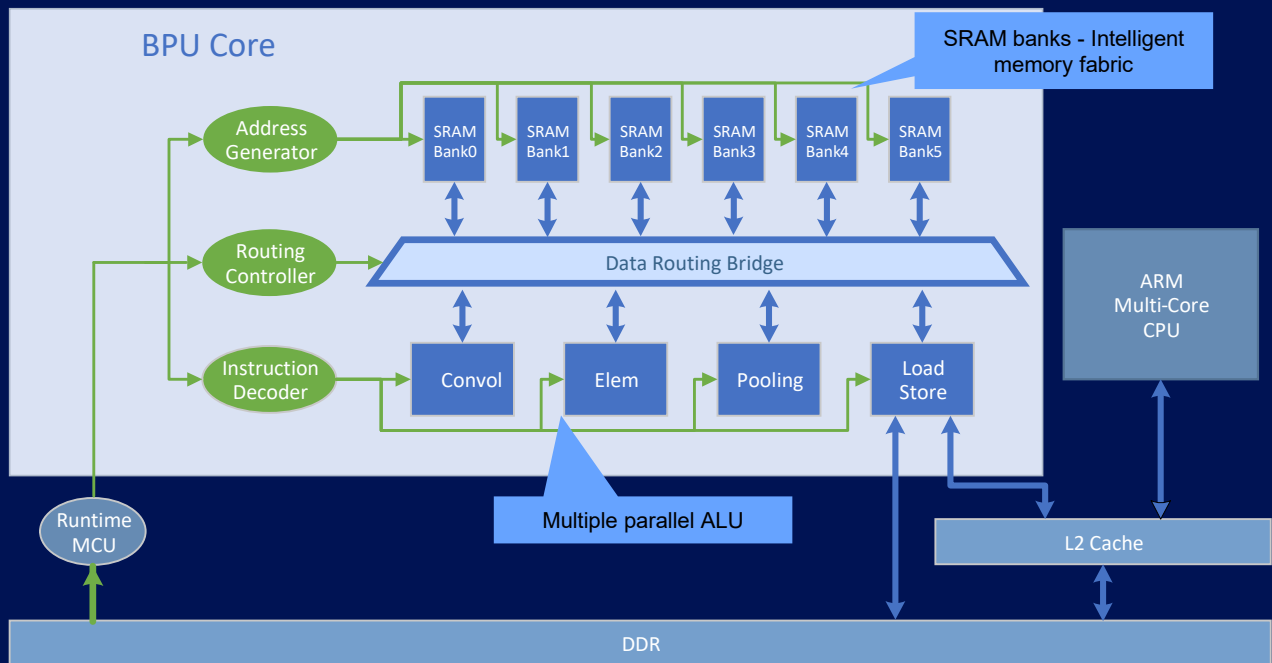
Waymo Open Dataset Challenges

<p>Challenge 1 </p> <h3>3D Detection</h3> <p></p> <p>Given one or more lidar range images and the associated camera images, produce a set of 3D upright boxes for the objects in the scene.</p>	<p>Challenge 2 </p> <h3>2D Detection</h3> <p></p> <p>Given a set of camera images, produce a set of 2D boxes for the objects in the scene.</p>	<p>Challenge 3 </p> <h3>3D Tracking</h3> <p></p> <p>Given a temporal sequence of lidar and camera data, produce a set of 3D upright boxes and the correspondence between boxes across frames.</p>	<p>Challenge 4 </p> <h3>2D Tracking</h3> <p></p> <p>Given a temporal sequence of camera images, produce a set of 2D boxes and the correspondence between boxes across frames.</p>	<p>Challenge 5 </p> <h3>Domain Adaptation</h3> <p></p> <p>Similar to the 3D Detection Challenge, but we provide additional segments from a new location and only a subset have labels.</p>
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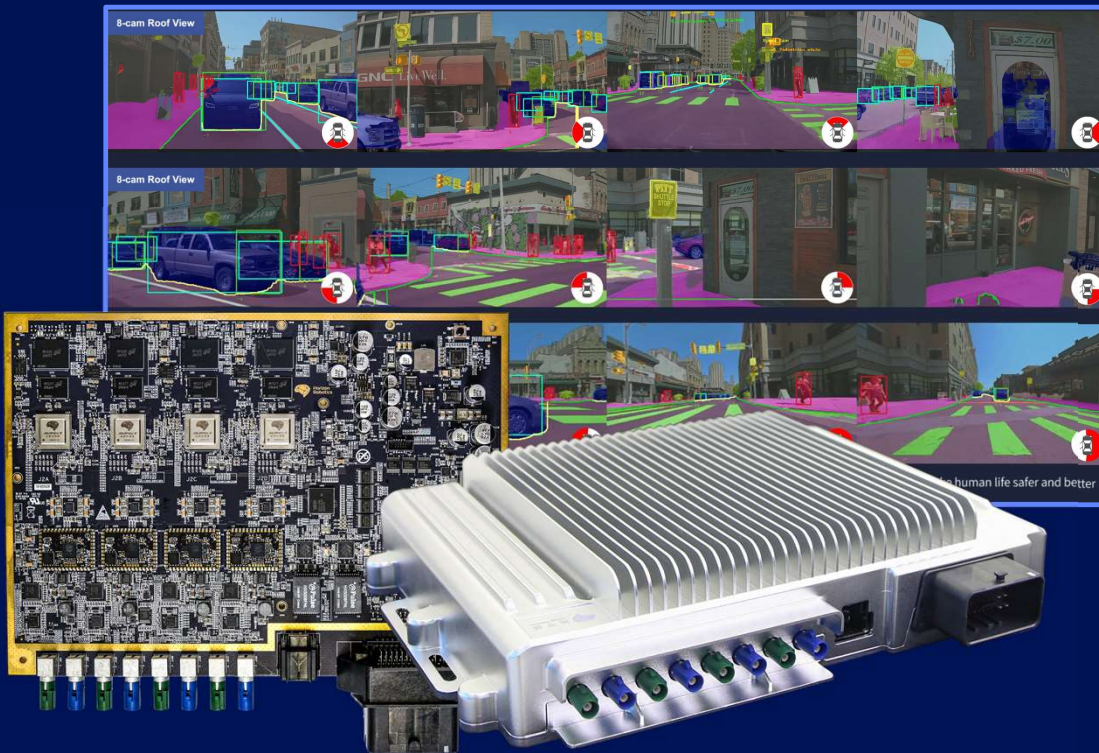
<https://blog.waymo.com/2020/07/opendataset-challenge-winners.html>

Horizon BPU: The Bernoulli v2 Architecture

- Dual core BPU (Brain Processing Unit)
- Natively designed for deep learning
- MIMD
- Maximize memory reads/writes in BPU
- Parallel computation with multiple ALUs
- The Horizon Difference
 - VS Nvidia: Significantly higher efficiency
 - VS Mobileye: Native deep learning support
 - VS Tesla: Open Ecosystem
- Result: High performance with low latency



Perception Compute System Expertise



Matrix 2

Modalities

- Vision perception
- LiDAR perception
- Localization and Mapping

Hardware:

- 4x1080P camera input @30fps
- Passively cooled 22W system. Ready for in-vehicle operation
- Tested to ISO-16750 and Ip51 for ingress protection
- Low latency (end to end: 100ms)

Algorithms:

- Semantic segmentation of 23+ categories
- 3D detection of vehicles and pedestrians
- Traffic light, traffic sign, road sign recognition
- Lane and free space parsing
- Robustness functions


Integration Tools:

- Hardware-in-Loop Test Kit
- Raw data collection system (framegrabber)
- AI Training Toolchain for custom network deployment
- Multi-platform reference design

ISO 26262 ASIL D Process Certification



ASIL D certification for SOC development process – Sept 2020



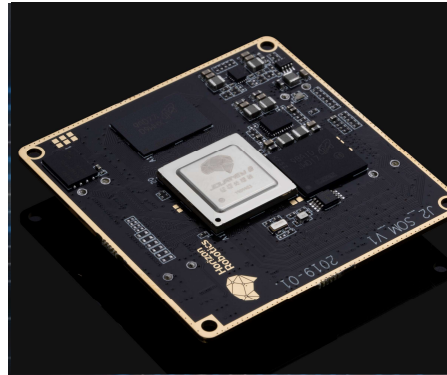
Horizon is member of ISO 26262 standard working group (ISO-TC22SC32-WG8)



Horizon Efficient AI Platform For Autonomous Machines



Journey Auto grade,
edge AI Processor,
with domain specific
Deep Learning dual
core “BPU”*



Open AI toolkit for NNs
training, quantization,
optimization and
deployment on the
“BPU”

Vehicle-ready, scalable,
passively cooled, with
processor and
algorithms: Matrix
perception computer



Matrix 2



Co-designed and co-
optimized, state-of-
the-art AI algorithms
for camera and LiDAR
perception + Mapping
and localization

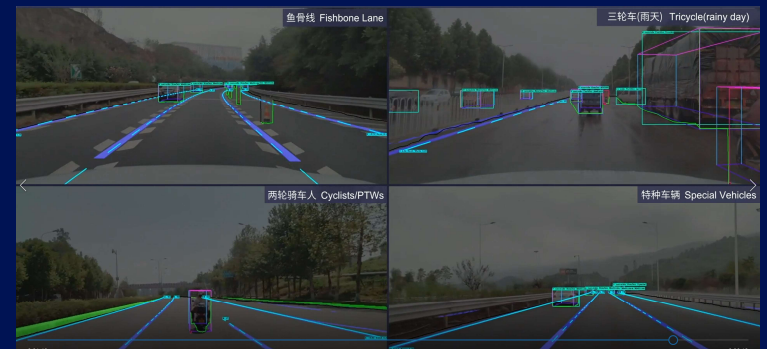
(*) BPU: Brain Processing Unit

Comprehensive Front Vision Perception

Horizon AI technology enables more features, more flexibility and better overall perf. than classic CV



- One Journey AI processor
- Less than 3W
- Horizon Vision Perception:
 - Detection/Classification/Semantic parsing
- 3D detection for vehicles/cyclist/motorbikes
- Less than 60ms latency
- Robustness features/ODDs
- Support Euro NCAP post-2020
- General cases. Corner cases. Special objects



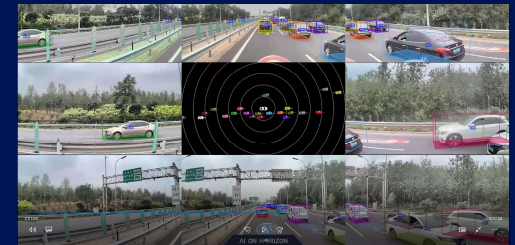
Comprehensive Deep Learning Based Perception

Horizon AI technology enables more features, more flexibility and better overall perf. than classic CV



- 00 road
- 01 background
- 02 pole
- 03 traffic_sign
- 04 traffic_light
- 05 road sign
- 06 traffic_lane
- 07 pedestrian
- 08 two-wheel
- 09 vehicles
- 10 fence
- 11 sky
- 12 cone
- 13 barrel
- 14 crosswalk
- 15 traffic_arrow
- 16 safety_area
- 17 stop_line
- 18 yield mark
- 19 speed mark
- 20 diamond
- 21 bicycle_sign
- 22 speed_bumps

- L4 surround vision
- 8x narrow FOV + 4 fisheye
- Horizon perception:
 - Detection. Classification
 - Semantic parsing
- 3D vehicles/cyclist/motorbikes
 - Vehicles: 6 types, 150m
- Traffic sign: 376 types in US
- Traffic light: 3 colors + off + more
- Lane line: 4 types and 2 colors
- Pedestrians/Cyclists: 80m
- Latency < 100ms
- Multicam 3D detection and tracking
- Day and night scenes



LiDAR and Camera Perception and Fusion

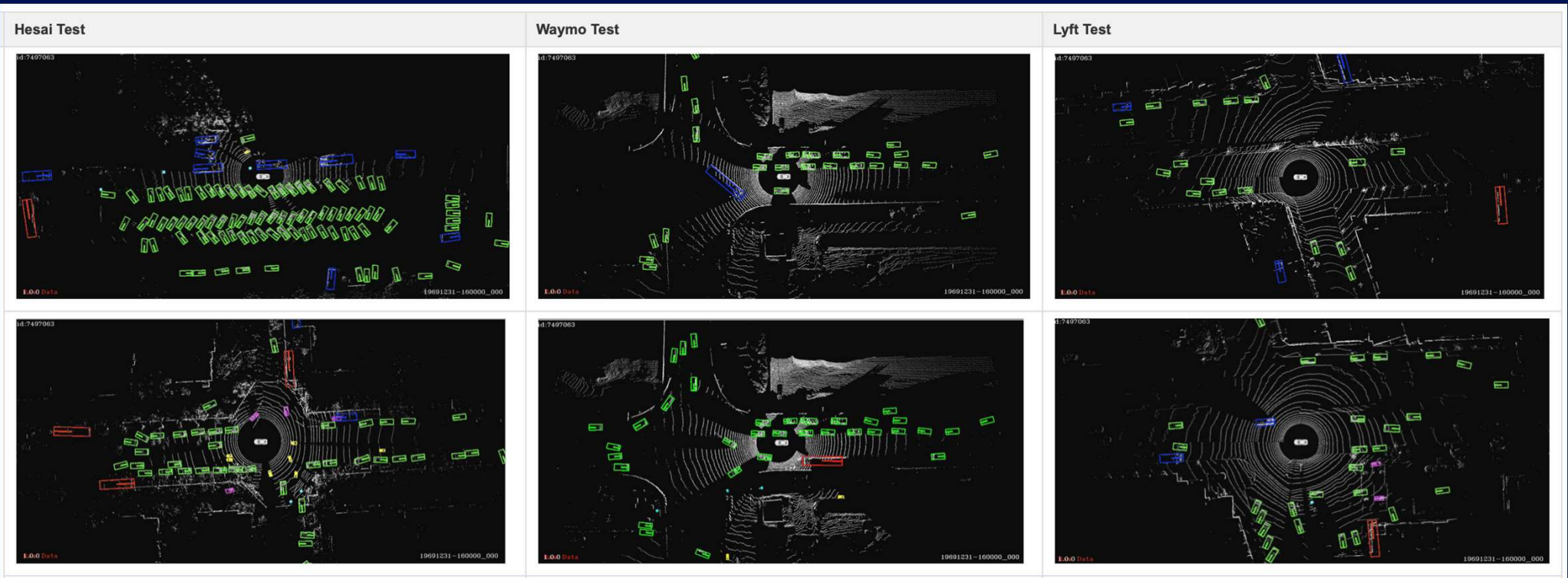


- LiDAR 3D object detection and tracking
- 1x Journey processor
 - CPU: ~40% Utilization
 - BPU: ~90% Utilization (one core)
 - Performance: up to 44 FPS
- Detection range:
 - Longitudinal [-100m, 100m]
 - Lateral [-50m, 50m]
- 6x Camera semantic parsing (mult. proc)
- Fused output. Improved perception robustness through multi-sensor fusion



Algorithm Generalization

Detector trained on one LIDAR/Dataset can generalize to a different LIDAR/Dataset

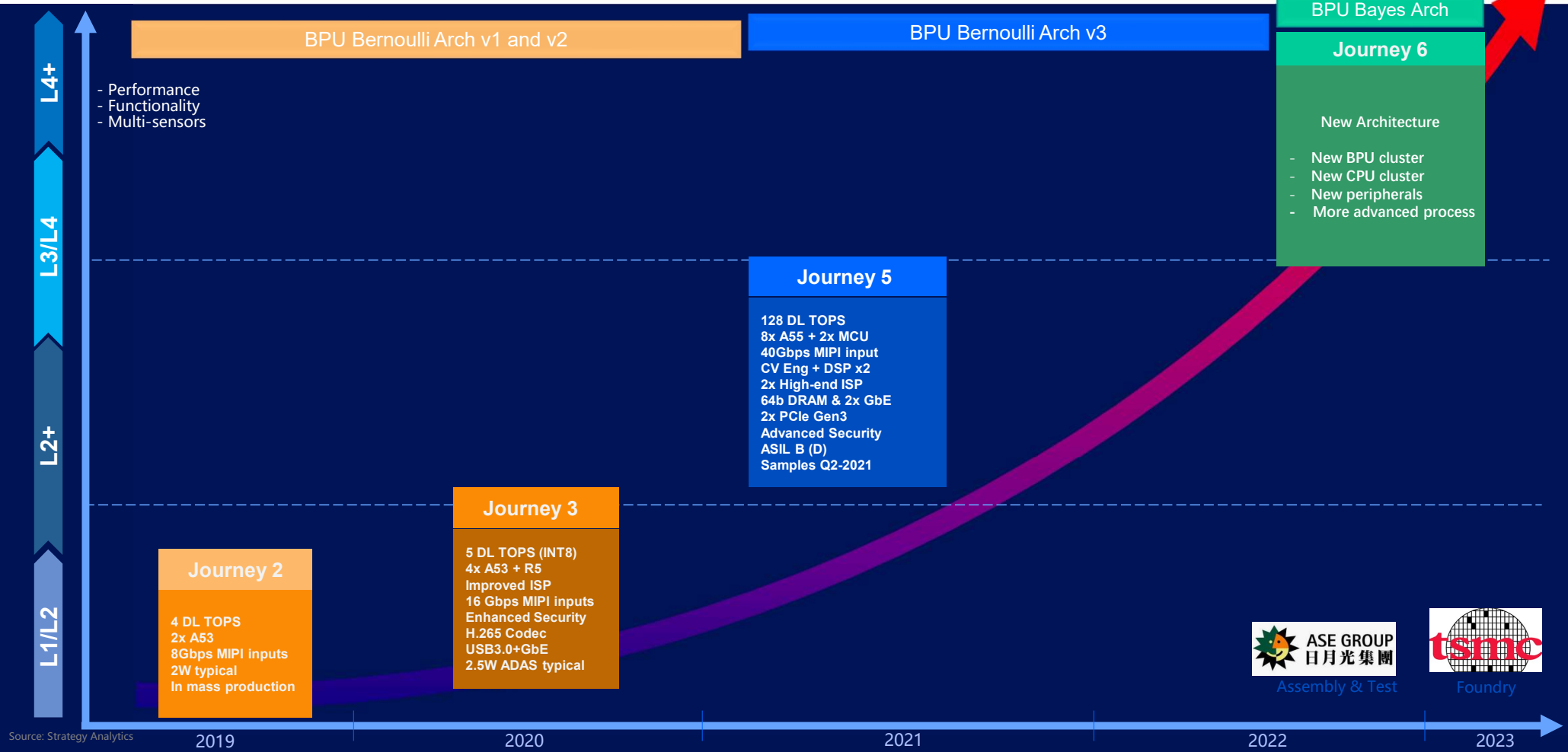


Multimodal Solutions For Smart Cockpit



- Horizon Halo™ Multimodal solutions
- Calling security alert
- Auto lower console volume
- Distraction alert
- Mild, moderate and heavy fatigue mitigations
- Smoking detection and mitigations
- Cockpit selfie

Journey AI Processors Family



Source: Strategy Analytics

Journey 3 New AI Processor



Computation Specs:

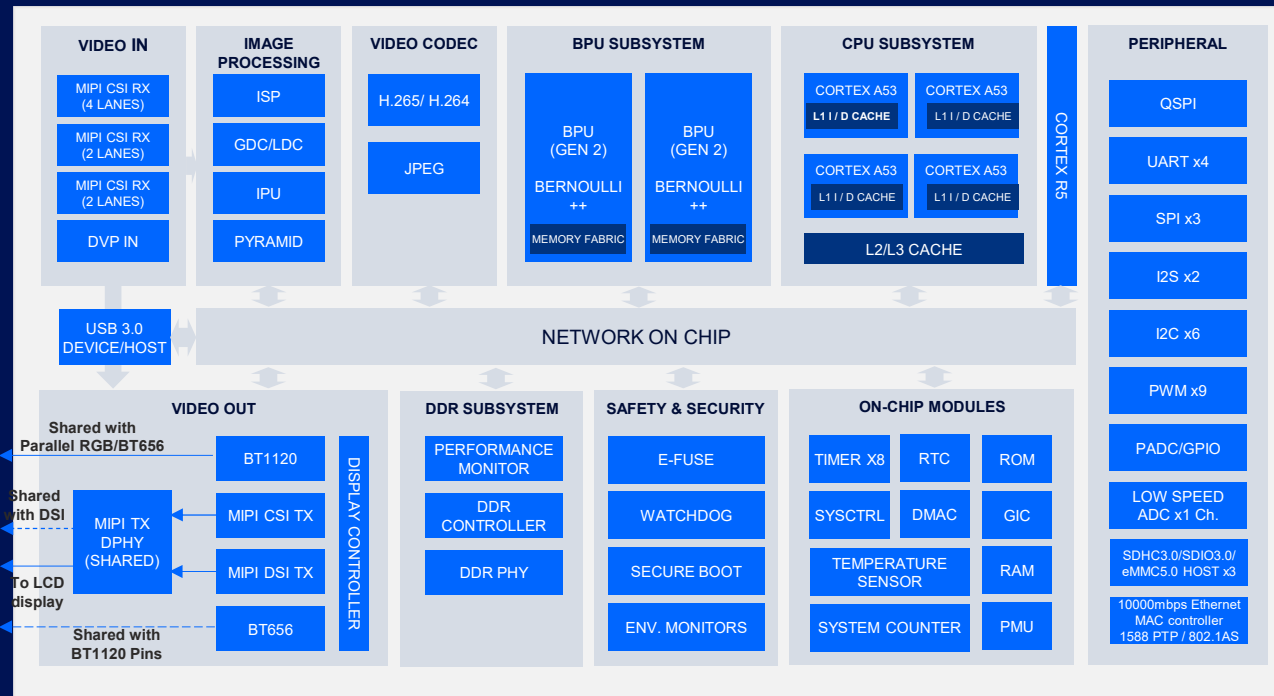
- Quad Cortex-A53
- Single Cortex-R5 assistant
- Dual BPU™ @ 5 DL TOPs
- On-chip ISP support HDR
- High perf. Video codec 4K60 (H.264/H.265, JPEG)
- DDR4/LPDDR4/LPDDR4X

Physical Specs:

- 2.5W Typical ADAS workload
- TSMC 16nm FinFET
- AEC-Q100 Grade 2
- 15x15mm, FCBGA484 Package

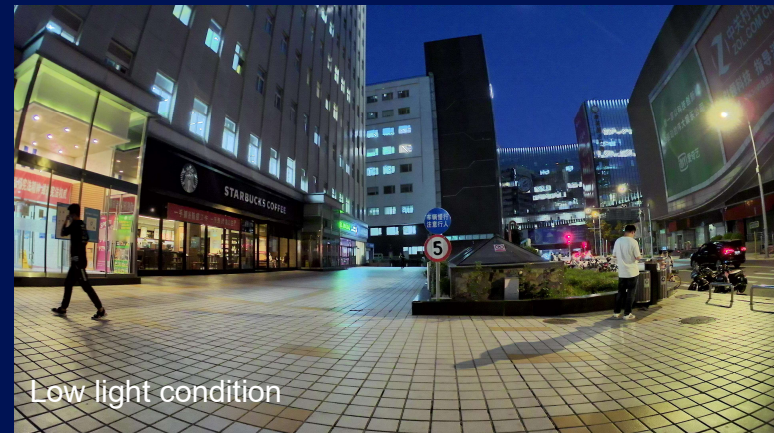
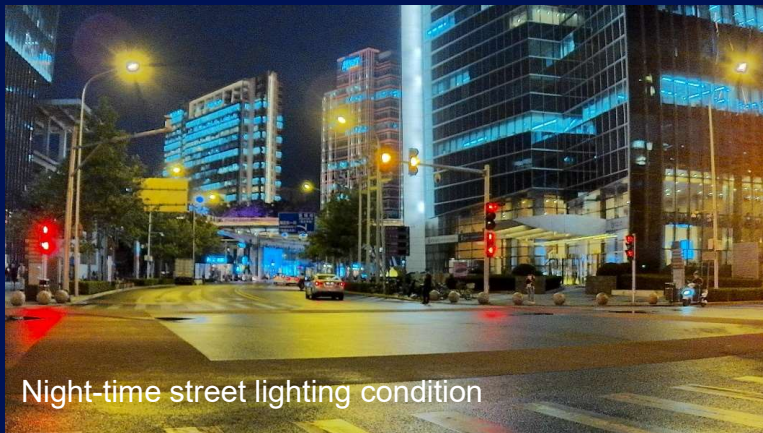
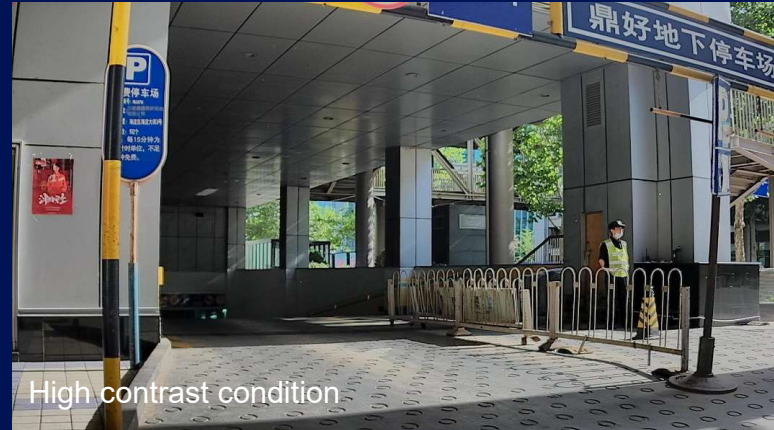
Other Features:

- MIPI CSI-2 – Up to 16 Gbps
- Gigabit Ethernet TSN
- USB 3.0
- HW Crypto/Secure Boot



Perception Starts with Great Image Quality

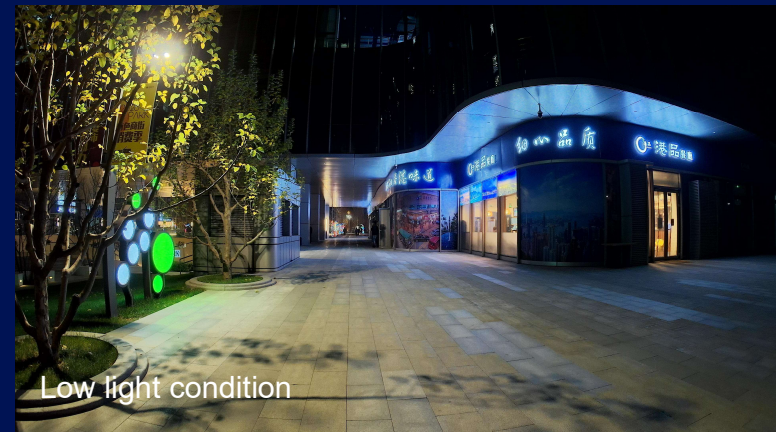
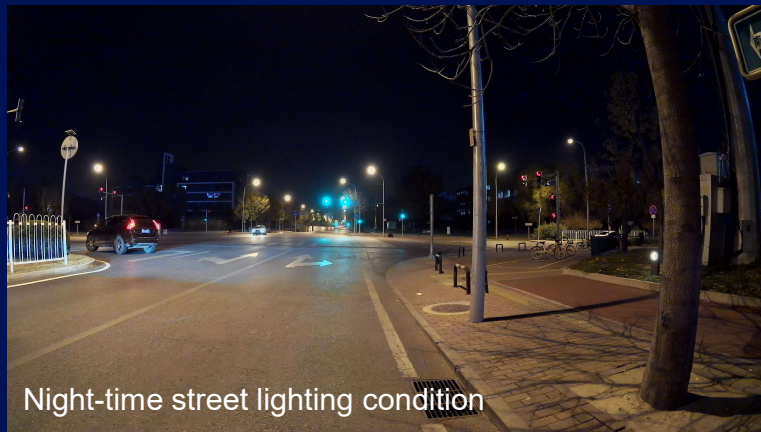
Journey 3 on-chip ISP delivers outstanding performance*



* For AR0820 RCCB (8MP)

Perception Starts with Great Image Quality

Journey 3 on-chip ISP delivers outstanding performance*



* For AR0820 RGGB (8 MP)

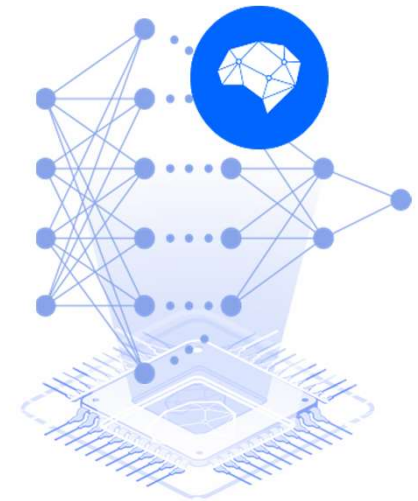
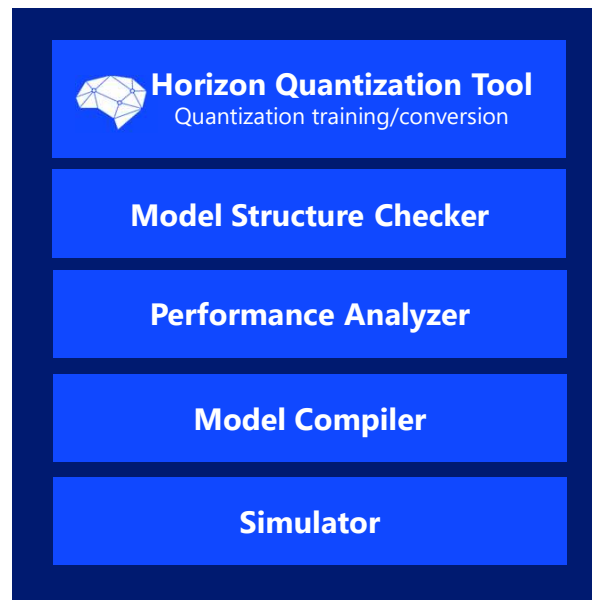
Easy-to-Use AI Toolkit for Developers

OpenExplorer

Development platform provided for customers to train and deploy their existing algorithm models and create their algorithm differentiation



Caffe



Powerful Tools, Simple APIs and Sample Code

Model Conversion

Post-training Quantization:

- Flt. Pt to Fix pt. conversion
- No retraining required
- Fast and easy
- Minimum accuracy loss
- Caffe native. TF and PyTorch via ONNX

Quantization-aware Training

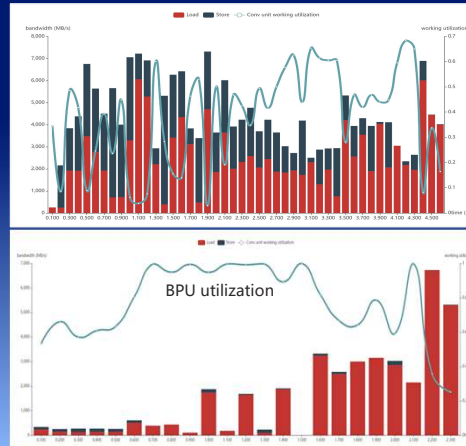
- MXNet and TF plugins. PyTorch planned
- Retraining required
- Flexible to adjust model structure
- Fully recovered accuracy



Performance Optimization

Performance Compiler:

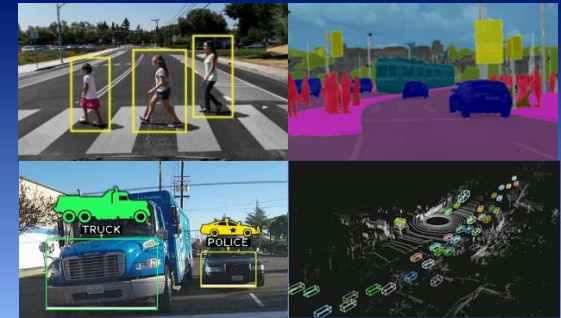
- Compiler automatic optimization
- Performance visualization
- Convolution-level operation details
- Diagnose tool of quantization loss
- Model deployment simulator



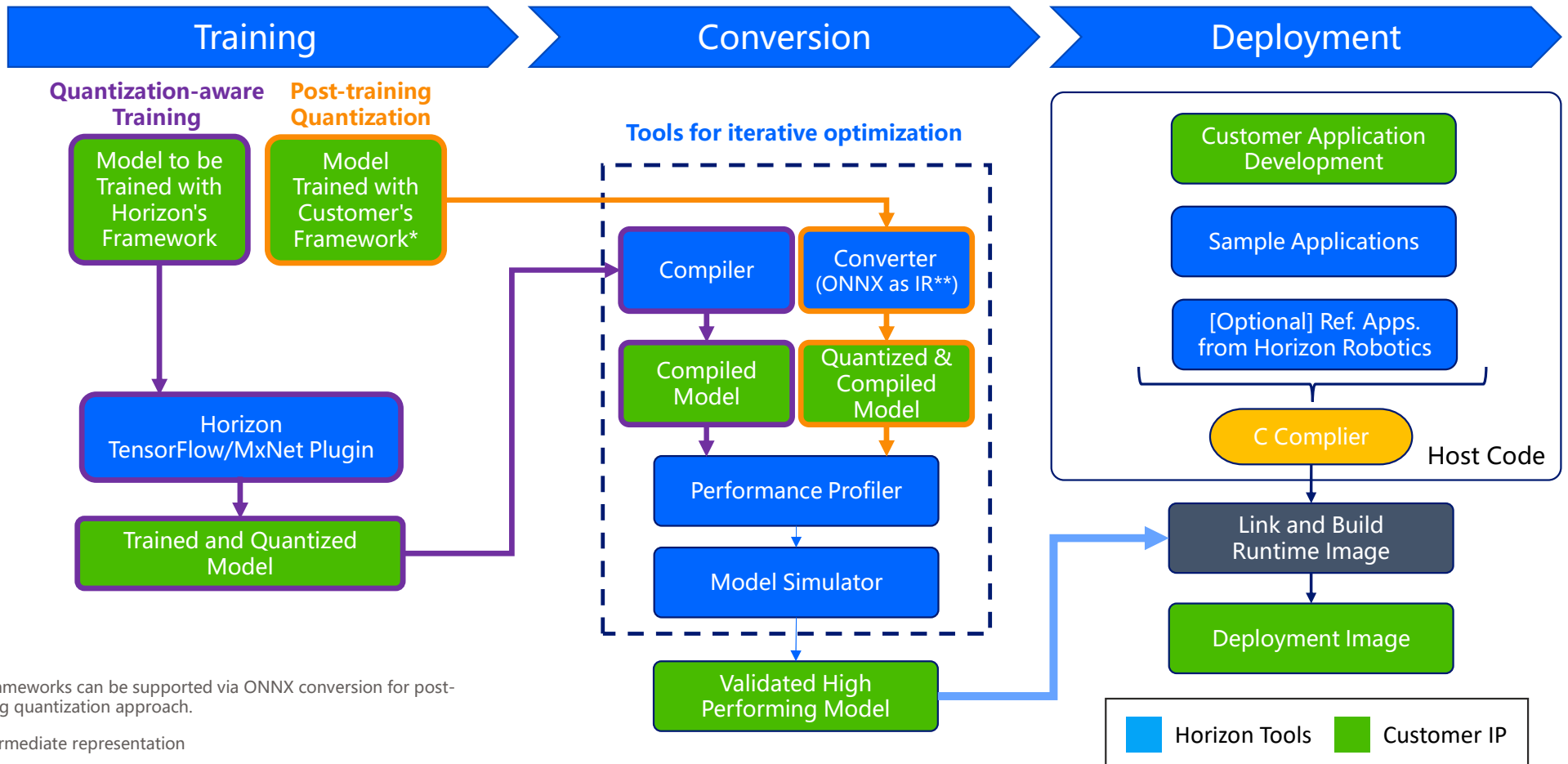
Deployment

Runtime SDK:

- High level API (BPU, ISP, Multimedia) for rapid development
- Low level APIs (Runtime, VIO, TaskMgr) for more flexibility
- Performance test tools
- Quick start guide and manuals
- Sample models and applications (detection, classification, segmentation, LiDAR)



Workflow

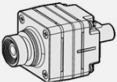
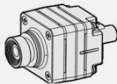


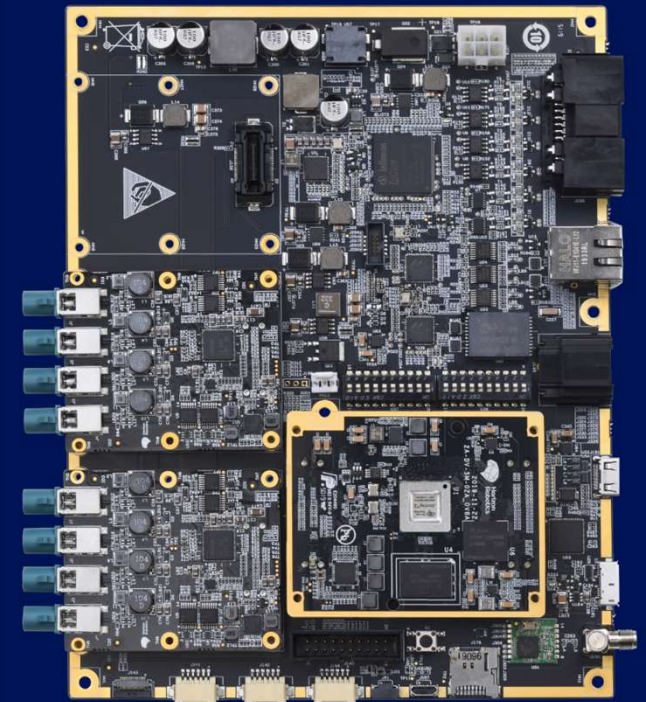
*All frameworks can be supported via ONNX conversion for post-training quantization approach.

**Intermediate representation

Journey 3 Development Board (J3-DVB)

- Quick access to the capabilities of Journey 3's powerful architecture.
- Hardware environment with rich peripherals & features.
- Powerful tools to easily develop applications on Journey 3.

Camera Type	Effective Focal Length	Lens View Angle	Image Size
 OV10635 (Available via Horizon)	5.47mm 1.33mm	H (59°) V (36°) H (192°) V (129°)	1280x800
 AR0233 (Available via 3 rd Party)	3.43mm	H (103°) V (57°)	1920x1080
 IMX390 (Available via 3 rd Party)	5.5mm 1.83mm	H (61°) V (34°) H (186°) V (105°)	1920x1080
 AR0820 (Available via 3 rd Party)		Planned	



Key Performance Indicators



Algorithm accuracy reflected on dedicated tasks

Direct association between AI performance and functions/tasks

Image Classification (ImageNet) : accuracy, TOP-1, TOP-5
Detection (COCO) : mAP

Speed

Latency

Throughput

FPS (Frame Per Second)

Efficiency

Cost

Power Consumption

MAPS: Mean Accuracy-guaranteed Processing Speed



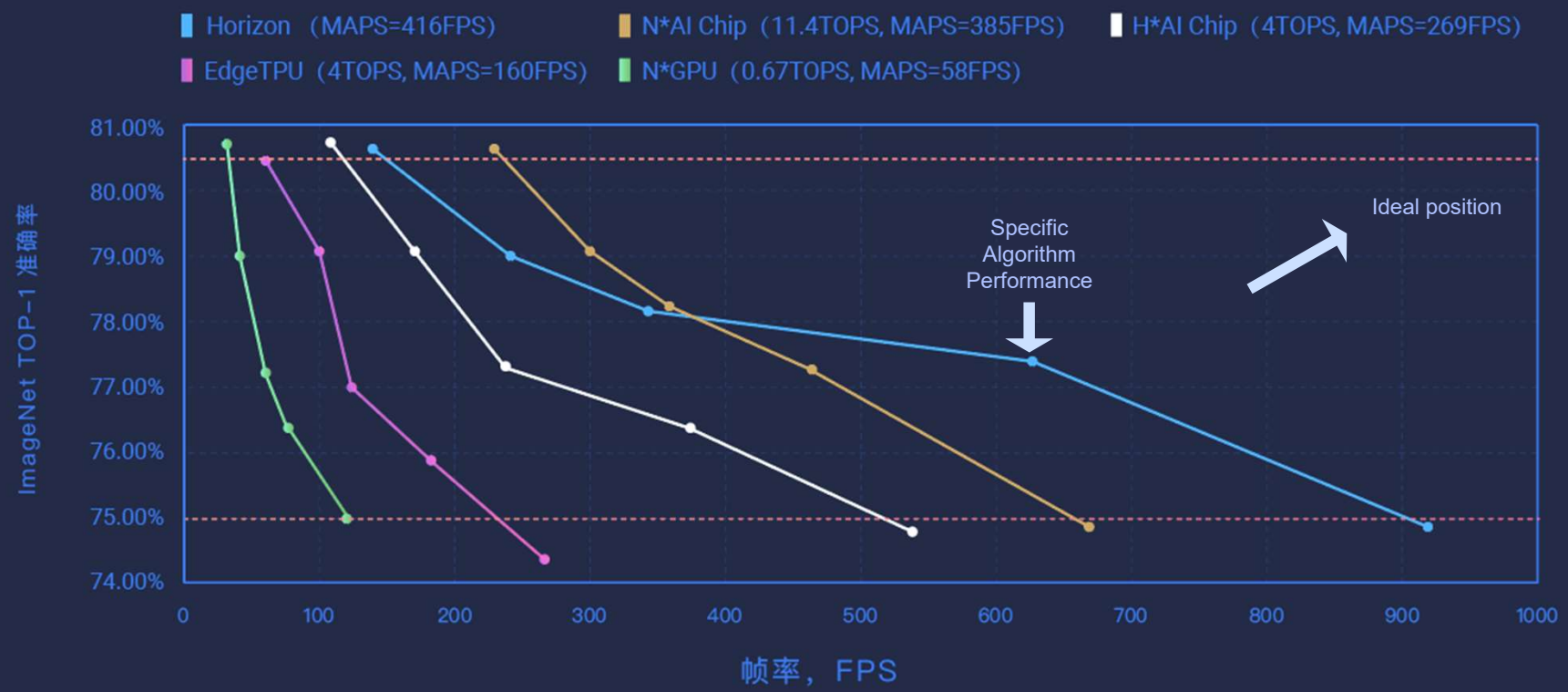
A New Metric for Fair Performance Evaluation

Comprehensive: Considers both accuracy and speed, from algorithm to processor.

Fair: Compares the best-supported models of each processor.

Application-oriented: Only cares about performance within acceptable accuracy range.

Machine Learning CV Task: ImageNet Classification MAPS



A Fair Representation of all Key Metrics





PRODUCTS

SOLUTIONS

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RESOURCES

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Efficient AI Computing For Autonomous Machines

Discover Horizon Robotics AI Inference Platform.
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Presented by [Deon Spicer](#)

Position: [Director of Business Development](#)

Email: deon.spicer@horizon.ai

Check our website: [//https://horizon.ai/](https://horizon.ai/)



Hardware Scalability for Mass Production

Fast time to market



Matrix Compute System

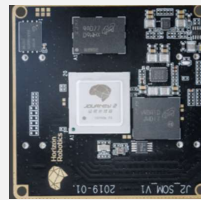
Robust Turnkey Solution

Immediate deployment

Modular, "Plug & Play"

No HW development needed

Module solution



Journey SOM

Balance of Scale & Ease of Design

3 - 6 months design time

Highly Flexible Architecture Design

IPC integration via daughter card

Customer board design



Journey SOC

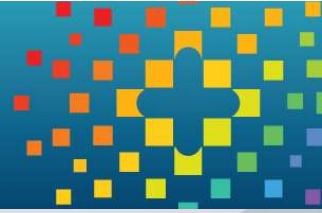
Most Cost Effective

12 - 18 months design time

Fully Flexible Architecture Design

Chip-down integration into PCB

Empowering Product Creators to Harness Edge AI and Vision



The Edge AI and Vision Alliance (www.edge-ai-vision.com) is a partnership of ~100 leading edge AI and vision technology and services suppliers, and solutions providers

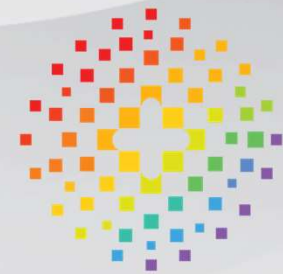
Mission: To inspire and empower engineers to design products that perceive and understand.

The Alliance provides low-cost, high-quality technical educational resources for product developers

Register for updates at www.edge-ai-vision.com

The Alliance enables edge AI and vision technology providers to grow their businesses through leads, partnerships, and insights

For membership, email us: membership@edge-ai-vision.com

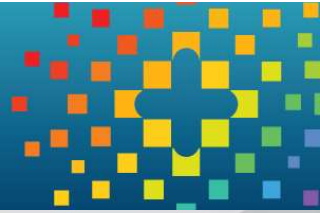


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- *“Wonderful speakers and informative exhibits!”*

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