

The logo for the 2021 Embedded Vision Summit Virtual. It features the year '2021' in a light blue font at the top. Below it, the word 'embedded' is in a smaller, dark blue font. The word 'VISION' is in a large, bold, dark blue font, with the letter 'O' replaced by a colorful circular graphic composed of many small dots. Below 'VISION' is the word 'summit' in a dark blue font. At the bottom, the word 'VIRTUAL' is in a green font, followed by a vertical bar and the dates 'MAY 25-28' in a light blue font. The entire logo is set against a white background with a subtle grid pattern, which is itself centered on a larger graphic of overlapping green and yellow geometric shapes.

2021
embedded
VISION
summit®
VIRTUAL | MAY 25-28

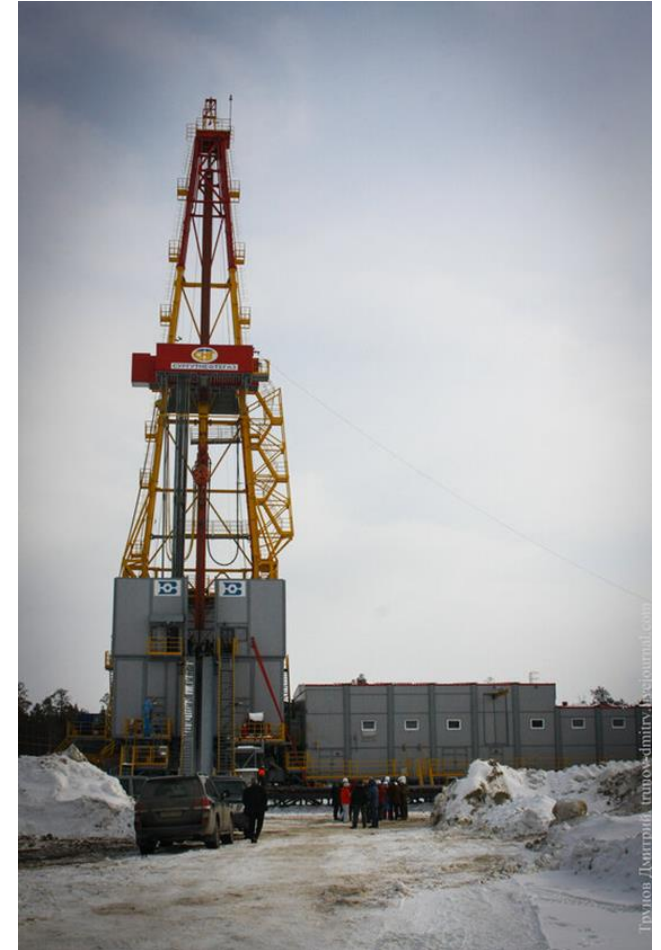
Developing Edge Computer Vision Solutions for Applications with Extreme Limitations on Real-World Testing

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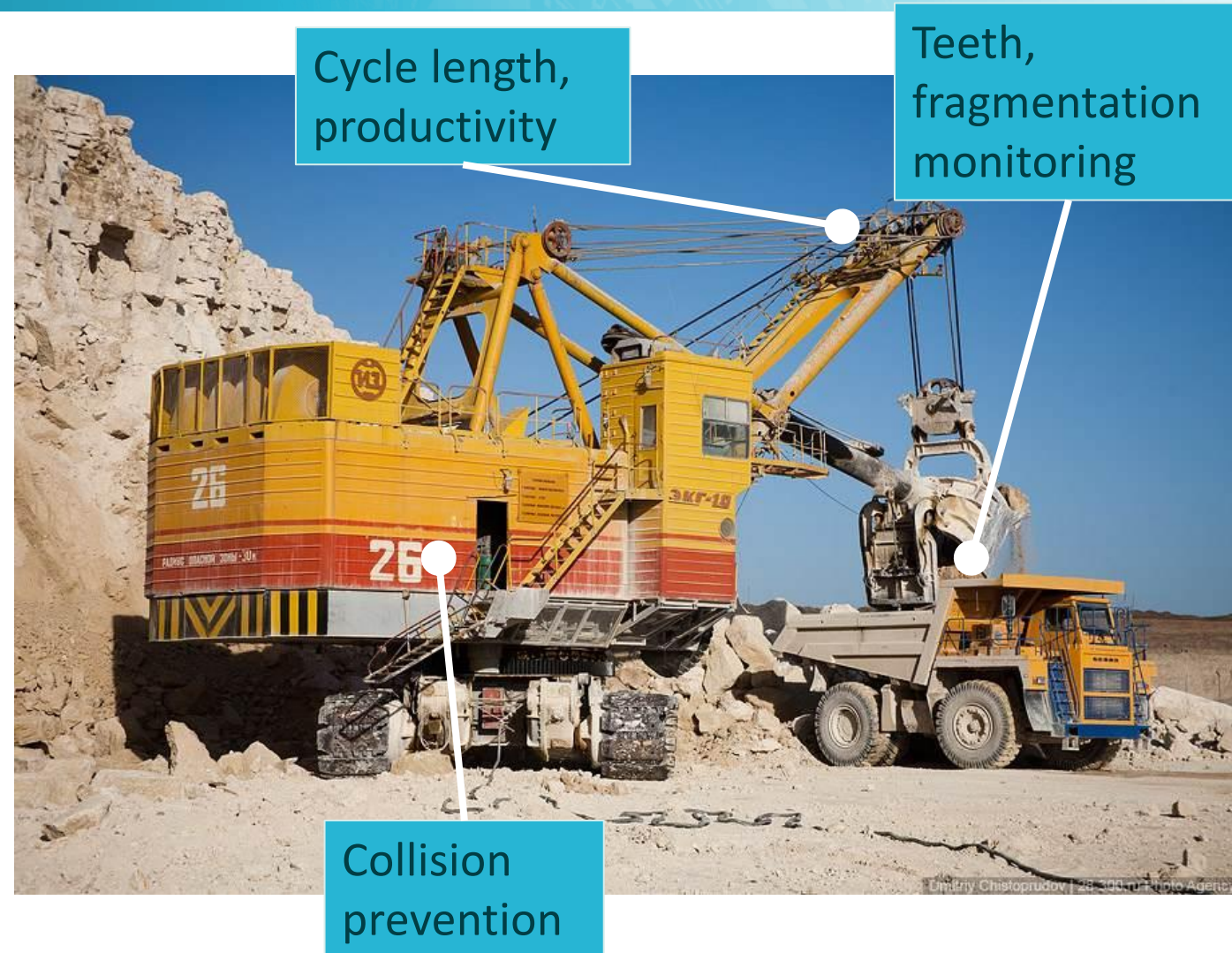
An example of oil well drilling safety analytics

- **10+ safety violations detecting with near real-time alerts**
- SLA 24/7 with low downtime
- 15 cameras, 40 people, nothing around for miles, 2 days to get there
- Only satellite connection, and it ain't Starlink
- Low bitrate (< 1 video stream, lots of packet loss)



An example of mining shovels monitoring

- **Monitoring teeth wear and loss, fragmentation in the bucket, cycle length**
- Wi-Fi mesh network working at random times with random speed
- Hardware access possible at semi-random time once per 1-2 month
- Surges, vibration, coal dust



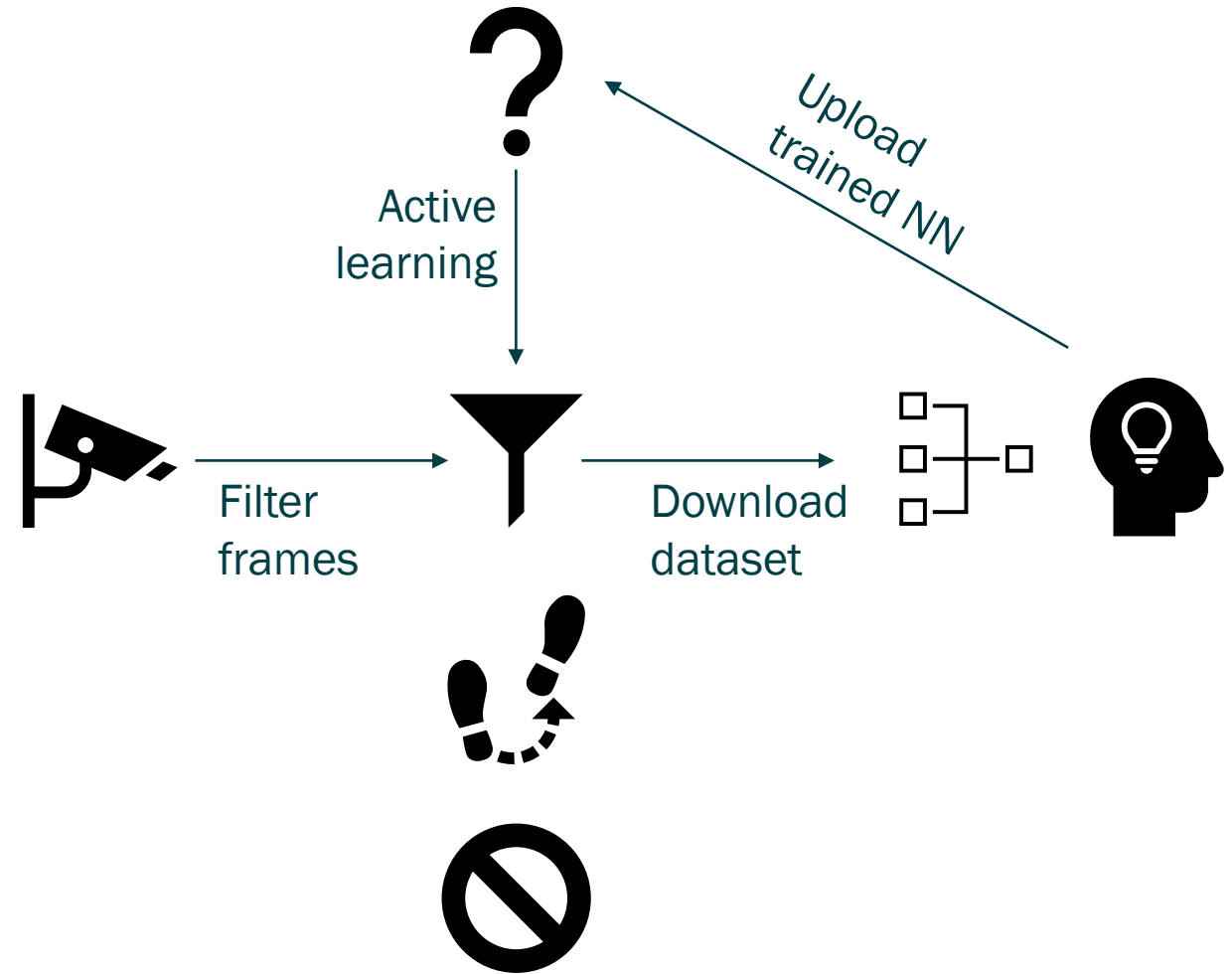
1. Getting the data from the edge device
2. Uploading software, including NN themselves
3. Some events are too rare to train
4. No room for error: hard to update, high cost of error



1. Getting the data from the edge device

Getting the data from the edge device

- Filter for blocked view, no movement, fog
- Active learning



Uncertainty sampling

The simplest and most common method for uncertainty sampling is to take the difference between 100% confidence and the most confidently predicted label for each item.

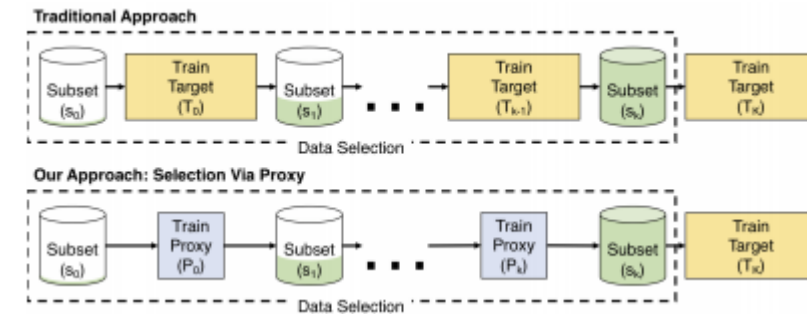
$$\phi_{LC}(x) = P_{\theta}(y^* | x)$$

Distort to confuse

Minimizing the sensitivity to perturbations with the idea of inducing “consistency”, i.e., imposing similarity in predictions when the input is perturbed in a way that would not change its perceptual content.

$$\mathcal{L}_u(x, M) = D(P(\hat{Y} = \ell | x, M), P(\hat{Y} = \ell | \tilde{x}, M)),$$

Proxy ranking

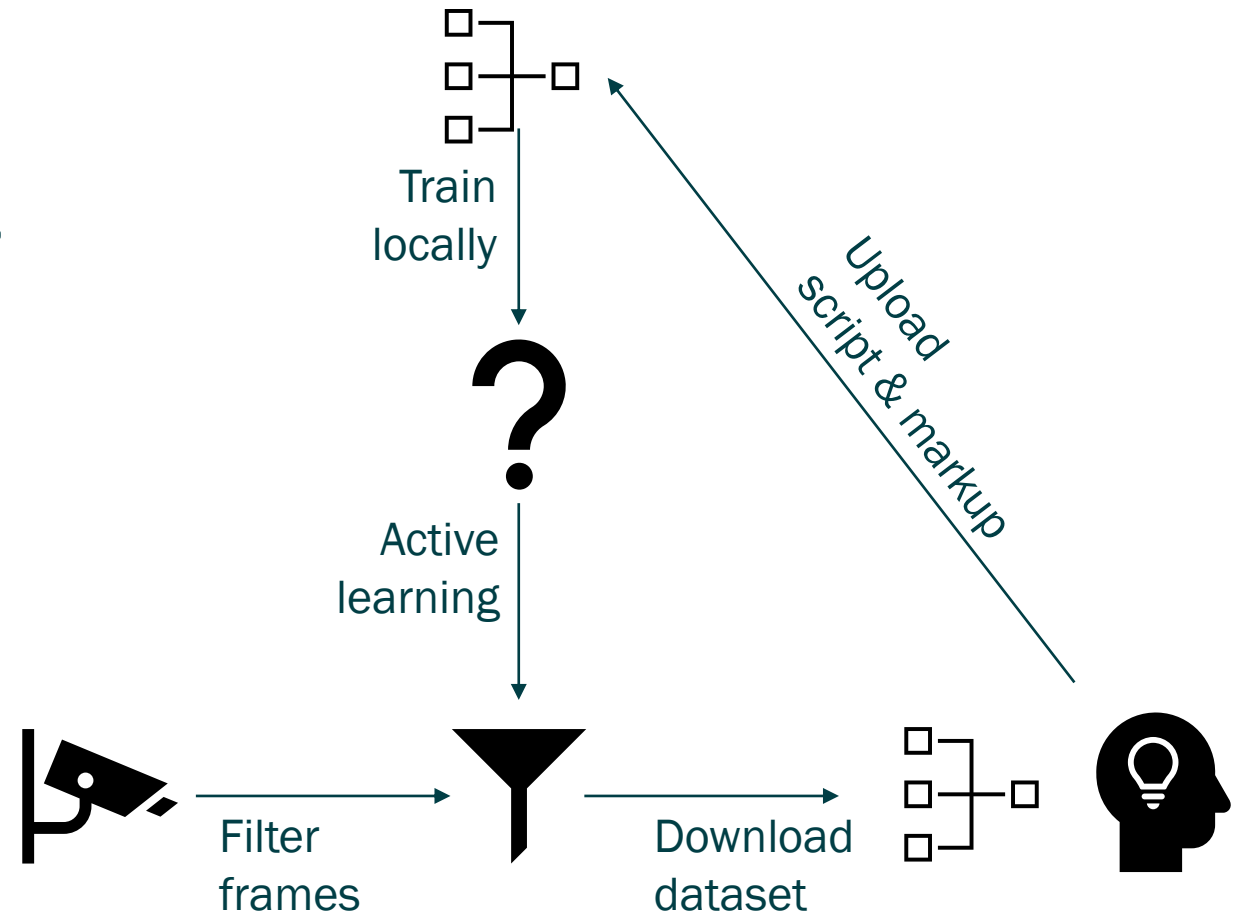




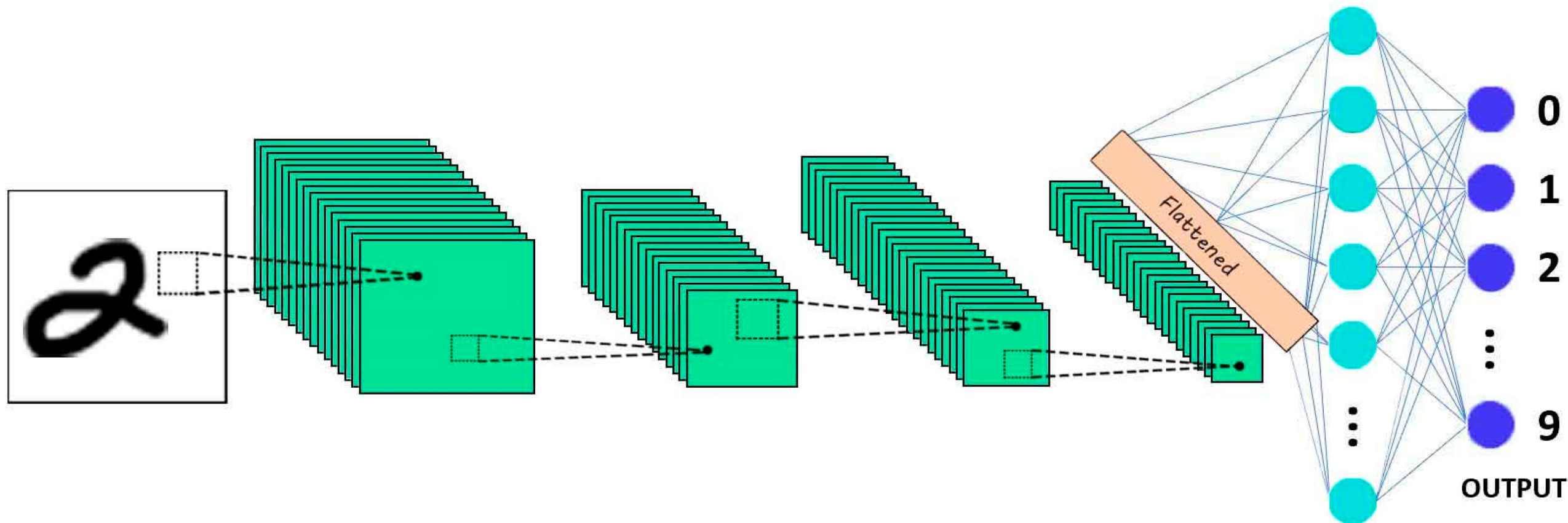
2. Uploading software, including NN themselves

Uploading software, including NN themselves

- Training on the edge devices themselves, upload only script and markup (batch size could be smaller due to memory limitation)
- Upload NN diff (only changed bits)



Why uploading NN diff is working



1. Further back – less changes

2. Maybe training only FC



3. Some events are too rare to train

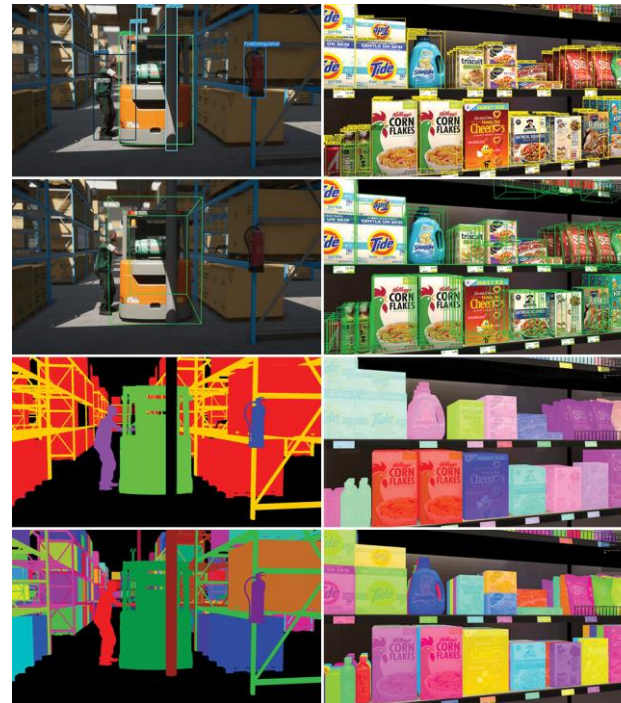
Some events are too rare to train

- **Using administrative resource to stage the events**
- **Using mannequin**
- **Generate more data:**
 - 'Style transfer' say from Minecraft
 - 3D-modelling
 - GANs

'Style transfer' say from Minecraft



3D-modelling



GANs





4. No room for error: hard to update, high cost of error

No room for error: hard to update, high cost of error

- **Monitoring:**
 - Direct light, blockage, shifting
 - Event distribution
- **Full simulation of hardware and software**
- **Reserve infrastructure**
- **Auto-restart, auto-rollback**





Wrap Up

Main takeaways

1. Expect development costs 50% higher
2. Expect to spend the delta on DevOps
3. Figure out the network and data transfers limits

Resource Category 1

Papers mentioned

<https://yadi.sk/d/QtogGW0j64Ea4w>

FUNIT project page

<https://nvlabs.github.io/FUNIT/>



Thank you