

## Optimized Vision Language Models for Intelligent Transportation System Applications

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#### Introduction

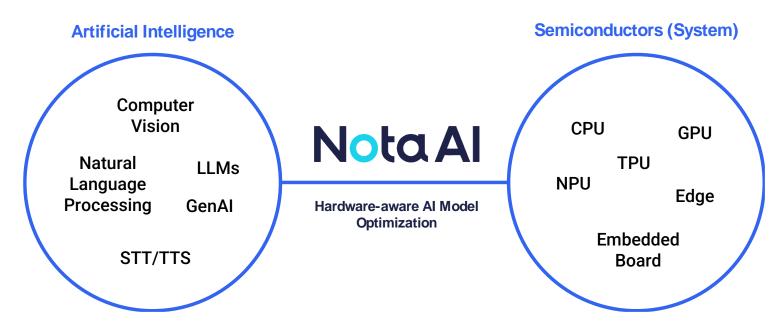


- In this talk, we explore the challenges in ITS.
- How vision language model (VLM) can solve these challenges.
- Future work will also be addressed.



## **Identity of NotaAl**



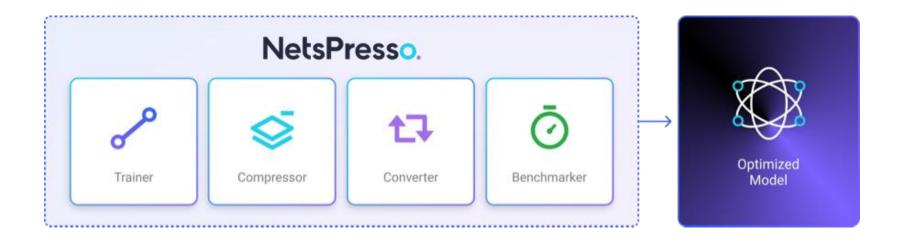


Nota AI bridges the gap between AI & semiconductors.



#### **Nota Al's Main Product: NetsPresso**





NetsPresso® simplifies AI model optimization for target devices with automated processes.



## Platform & Edge Solutions: Elevating Excellence





Using NetsPresso, Nota AI also has created a solution business in ITS



## **NotaAl's Expertise**



#### **LLM Optimization**

#### LLaMA-7B -- LLM-Pruner 4.9B Batch size (B) = 1 8192 B128 4096 Throughput (tokens/s) 2048 2048 256 128 2.7 ₩B32 Latency (s) LLaMA-7B FLAP (Width) LLM-Pruner (Width)< Ours (Depth⊶) 1.8 25.6 12.6 ₫B1 64 32 1.6 3.4 4.3 5.2 6.1 7 # Parameters Latency (s)

#### **Stable Diffusion Optimization**



4.0s (-29%)

3.9s (-29%) 3.9s (-29%)

Nota AI also specializes in GenAI compression



iPhone 14

**Intelligent Transportation System (ITS)** 



## **Enhancing Traffic Flow: Real-Time Lightweight ITS Solutions**





#### **Smart Intersection System**

Real-time incident detection and analysis for safe road condition



#### **VRU Safety Solutions**

Al-based real-time hazardous situation screening and control system



# Automatic Incident Management System

Real-time incident detection and analysis for safe road condition



#### **AI Smart Parking**

Real-time parking occupancy and parking facility utilization analysis



## **Use Case 1: Smart Intersection System**







- Daejeon metropolitan city ITS construction project
- Intersection CCTV AI video analysis (600 ch)
- 98% accuracy in traffic volume counting in night and rainy conditions

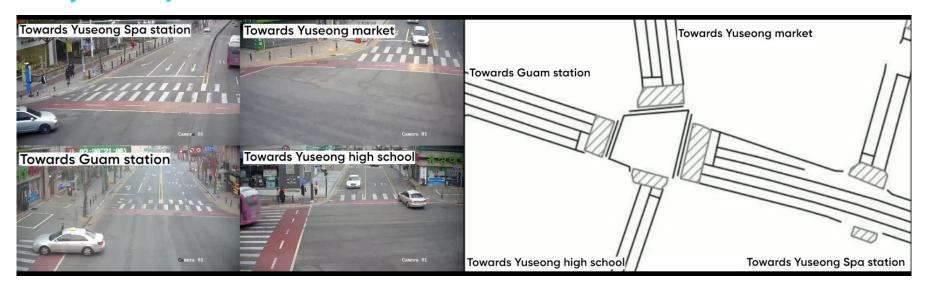


## **Use Case 2: Al Safe Crossing**



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#### Daejeon City | Implementing LDM using vehicle trajectory prediction information





## **Use Case 3: VRU Safety Solutions**



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National Highways | C-ITS: Al video analysis for smart crosswalk safety transmitted through V2X communication

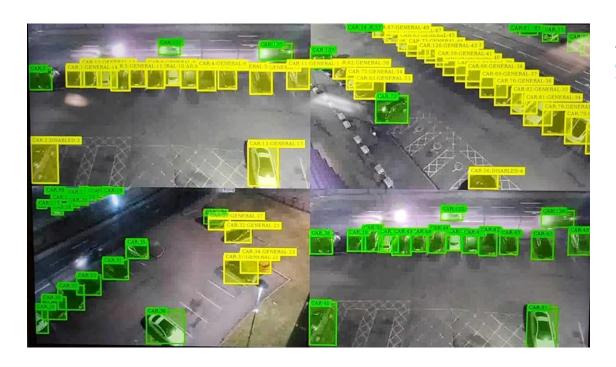




## **Use Case 4: AI Smart Parking**



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 USA San Diego outdoor parking management (Caltrans)



 UK Milton Keynes stadium outdoor parking management



## **Challenges in ITS**



- Ill-posed problem: How can we define "road debris"?
- Contextual problem: How can we define "accidents" with object detection?
- Rare dataset: How can we obtain dataset?



## **Ill-posed Problem: Road Debris**









Can it be detected by legacy AI models?



#### **Contextual Problem: Accident Detection**



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Can it be detected by legacy AI models?



## **Challenges in ITS**



- Ill-posed problem: How can we define "Road debris"?
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Requires super-generalized model: Foundation Model



## Foundation Model on the Edge: Challenges in Industrial Al



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#### As-is **Problem** Inference Result Rule-based algorithm is fragile. Logic added for new requirements. Logic Layer (Kalman filtering...) Errors on the object detection/tracking propagate to logic layers. On-site calibration. Data drift. Data acquisition on rare events is hard. Deep Learning Model Sophisticated model composition. On-site calibration. Input Image



#### Foundation Model on the Edge: Challenges in Industrial Al



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# To-be Inference Result Foundation Model (VLM)

Input Image

#### Features

- VLM is capable of comprehending complex scene.
- VLM already contains various logic.
- VLM is robust on data drift.
- VLM is aware of rare events.
- VLM needs less or no calibration.
- Still, VLM is not understanding video.

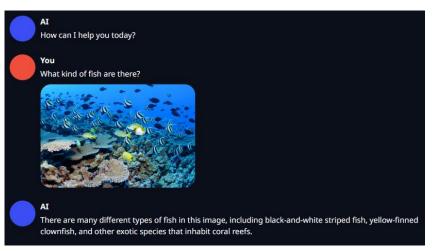


## Vision Language Model: LLaVA



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#### LLaVA Live LLaVA





Source: jetson-ai-lab.com



#### **Working Prototype of LLaVA on Accidents Detection**



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#### **Benchmark on Models**



Llava-13B (Jetson AGX Orin)	Quantization	Tokens/sec	Memory
text-generation-webui	4-bit (GPTQ)	2.3	9.7 GB
llava.serve.cli	FP16 (None)	4.2	27.7 GB
llama.cpp	4-bit (Q4_K)	10.1	9.2 GB
local_llm	4-bit (MLC)	21.1	8.7 GB

Source: jetson-ai-lab.com



#### **Future Work**



- More advanced optimization required
- VLM needs to comprehend temporal consistency
- Domain adaptation might be required for user specific scenario
- Interface for product required
- Prompt engineering is required for higher performance



#### Conclusion



- Industrial AI is already a widely used technology, but technology is limited when the problem is complex and underdetermined.
- Among GenAl models, a Vision Language Model (VLM) can understand complex scenes, so it could analyze complex queries and events.
- For example, in ITS, road debris and car accidents are severe problems, but this couldn't be solved by legacy AI models.
- Using VLMs, these problems can be solved as well.
- However, VLMs are still computationally expensive, so lightweight VLMs are required for the next step.



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Thank you for your attention!

